The pressure of surface-attached polymers and vesicles

Thomas Prellberg¹ and Aleks Owczarek²

¹Queen Mary University of London ²The University of Melbourne

$\Sigma\Phi$ International Conference on Statistical Physics 2014

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2 Exactly Solvable Models

3 Conclusion

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Outline



2 Exactly Solvable Models

3 Conclusion

Thomas Prellberg The pressure of surface-attached polymers and vesicles

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Surface-grafted polymers



A polymer grafted to a surface exerts pressure on it

Bickel et al, PRE 62 (2000) 1124

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Surface-grafted polymers



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Related to change of entropy

From Polymer to Lattice Model

Coarse-grained "beads on a necklace"



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From Polymer to Lattice Model

Coarse-grained "beads on a necklace"



Self-avoiding walk on a regular lattice



Some Notation



 C_n : number of *n*-step polymers

 $C_n(r)$: number of *n*-step polymers avoiding site at distance *r*

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Some Notation



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Pressure of polymer on surface

$$P_n(r) = -\log \frac{C_n(r)}{C_n}$$

Some Notation



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Pressure of polymer on surface

$$P_n(r) = -\log rac{C_n(r)}{C_n}$$

$$P_n(r) o P(r)$$
 as $n o \infty$

Some Notation



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Pressure of polymer on surface

$$P_n(r) = -\log \frac{C_n(r)}{C_n}$$

 $P_n(r)
ightarrow P(r)$ as $n
ightarrow \infty$ Gaussian chains (Bickel, 2000)

$$P_G(r) = rac{\Gamma(d/2)}{\pi^{d/2}} rac{1}{(r^2+1)^{d/2}}$$

SAW versus Gaussian chain



Directed Walk Models Dyck paths Adsorbing Dyck paths Area-weighted Dyck paths

Outline

Surface-grafted polymers

2 Exactly Solvable Models

- Directed Walk Models
- Dyck paths
- Adsorbing Dyck paths
- Area-weighted Dyck paths

3 Conclusion

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Exactly Solvable Models

Directed walk models

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Exactly Solvable Models

Directed walk models

• Directed walks (both/one ends grafted)

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Exactly Solvable Models

Directed walk models

• Directed walks (both/one ends grafted)



• Pairs of directed walks



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Exactly Solvable Models

Directed walk models

• Directed walks (both/one ends grafted)



• Pairs of directed walks



• Partially directed walks



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Exactly Solvable Models

Directed walk models

• Directed walks (both/one ends grafted)



• Pairs of directed walks



• Partially directed walks



Moreover, add contact weights, area weights, nearest-neighbour interactions, ... $(\Box \rightarrow \langle \Box \rangle \land \langle \Xi \rangle)$

Directed Walk Models Dyck paths Adsorbing Dyck paths Area-weighted Dyck paths

Much activity ensued ...

So far

- Directed walks with contacts
 - E J Janse van Rensburg and TP, J. Phys. A ${\bf 46}$ (2013) 115202
- Pairs of walks with contacts
 - E J Janse van Rensburg and TP, J. Phys. A 46 (2013) 115202
- Directed walks with area

A Owczarek and TP, J. Phys. A 47 (2014) 215001

• Partially directed walks with contacts

G Iliev, E J Janse van Rensburg, and TP, in preparation

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The next model to be done

• Interacting partially directed walks

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• Partially directed walks with contacts

G Iliev, E J Janse van Rensburg, and TP, in preparation

The next model to be done

• Interacting partially directed walks

Also

• Rooted self-avoiding polygons

F Gassoumov and E J Janse van Rensburg, J. Stat. Mech. (2013) P10005

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Dyck paths

Directed walks with both ends tethered $\Leftrightarrow \mathsf{Dyck}$ paths

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Dyck paths

Directed walks with both ends tethered \Leftrightarrow Dyck paths



• 2*n*-step Dyck paths are counted by the *n*-th Catalan number C_n

$$D_{2n} = C_n \equiv \frac{1}{n+1} \binom{2n}{n} \sim \frac{4^n}{\sqrt{\pi} n^{3/2}}$$

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Dyck paths

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• Exclude paths touching the surface at distance 2r

$$D_{2n}(r) = D_{2n} - D_{2r} D_{2n-2r}$$

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Dyck paths

• Compute pressure

$$P_{2n}(r) = \log \frac{D_{2n}(r)}{D_{2n}} = -\log \left(1 - \frac{C_r C_{n-r}}{C_n}\right)$$

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Dyck paths

• Compute pressure

$$P_{2n}(r) = \log \frac{D_{2n}(r)}{D_{2n}} = -\log \left(1 - \frac{C_r C_{n-r}}{C_n}\right)$$

• Limiting pressure

$$egin{aligned} P_{2n}(2r) &\sim rac{1}{\sqrt{\pi}(na(1-a))^{3/2}} & r = na, \ n o \infty \ P(r) &\sim rac{1}{\sqrt{\pi}r^{3/2}} & ext{first } n o \infty, ext{ then } r o \infty \end{aligned}$$

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Adsorbing Dyck paths

Surface contact weight z

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Adsorbing Dyck paths

Surface contact weight z



• Exact partition function

$$Z_n(z) = \sum_{m=0}^{\lfloor n/2 \rfloor} \frac{4m+2}{n+2(m+1)} \binom{n}{\lfloor n/2 \rfloor + m} (z-1)^m$$

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Adsorbing Dyck paths

Surface contact weight z



• Exact partition function

$$Z_n(z) = \sum_{m=0}^{\lfloor n/2 \rfloor} \frac{4m+2}{n+2(m+1)} {n \choose \lfloor n/2 \rfloor + m} (z-1)^m$$

Limiting pressure

$$P_n^D(z; 2\lfloor an/2 \rfloor) \simeq \begin{cases} \frac{8}{\sqrt{2\pi n^3 a^3(1-a)^3} \log^2(z-1)}, & \text{if } z < 2; \\ \frac{\sqrt{2}}{\sqrt{\pi na(1-a)}}, & \text{if } z = 2; \end{cases}$$

$$\log(z-1) + \frac{A}{12na(1-a)(z-1)(z-2)}$$
, if $z > 2$;

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for *n* even, with $A = (a^2 - a + 1)(z^4 + 8z^3 + 30z^2 - 32z + 16)$

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Area-weighted Dyck paths

Dyck paths weighted by enclosed area, area weight q



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Area-weighted Dyck paths

Dyck paths weighted by enclosed area, area weight q



• Replace the *n*-th Catalan number C_n by $C_n(q)$

$$C_0(q) = 1 \;, \quad C_{n+1}(q) = \sum_{k=0}^n q^k C_k(q) C_{n-k}(q) \quad n \geq 0$$

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Area-weighted Dyck paths

Dyck paths weighted by enclosed area, area weight q



• Replace the *n*-th Catalan number C_n by $C_n(q)$

$$C_0(q) = 1$$
, $C_{n+1}(q) = \sum_{k=0}^n q^k C_k(q) C_{n-k}(q)$ $n \ge 0$

• Pressure $P_{2n}(q, r)$ is now given by

$$P_{2n}(q,r) = -\log\left(rac{C_n(q) - C_r(q)C_{n-r}(q)}{qC_n(q)}
ight)$$

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Directed Walk Models Dyck paths Adsorbing Dyck paths Area-weighted Dyck paths

Are-weighted Dyck paths

G(t,q) is fairly well understood, $C_n(q)$ much less

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Directed Walk Models Dyck paths Adsorbing Dyck paths Area-weighted Dyck paths

Are-weighted Dyck paths

G(t,q) is fairly well understood, $C_n(q)$ much less

• Continued fraction representation

$$G(t,q) = rac{1}{1 - rac{t}{1 - rac{qt}{1 - rac{q^2t}{1 - \dots}}}}$$

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Directed Walk Models Dyck paths Adsorbing Dyck paths Area-weighted Dyck paths

Are-weighted Dyck paths

G(t,q) is fairly well understood, $C_n(q)$ much less

• Continued fraction representation

$$G(t,q)=rac{1}{1-rac{t}{1-rac{qt}{1-rac{q^2t}{1-\dots}}}}$$

Alternatively

$$G(t,q)=rac{A_q(t)}{A_q(t/q)}$$

where

$$A_q(t) = \sum_{n=0}^{\infty} \frac{q^{n^2}(-t)^n}{\prod_{k=1}^n (1-q^k)}$$

is Ramanujan's Airy function

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Directed Walk Models Dyck paths Adsorbing Dyck paths Area-weighted Dyck paths

Scaling for $q \rightarrow 1$

Scaling function near q = 1 and $t = t_c(1) = 1/4$

$$f(s) = \lim_{q \to 1^{-}} \left(2 - (1-q)^{-1/3} G(1/4 - s(1-q)^{2/3}, q) \right) = -2 \frac{\operatorname{Ai}'(4s)}{\operatorname{Ai}(4s)}$$

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Bulk pressure

Compute pressure in the bulk using surface contacts

• Weight surface contacts by z



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Directed Walk Models Dyck paths Adsorbing Dyck paths Area-weighted Dyck paths

Bulk pressure

Compute pressure in the bulk using surface contacts

• Weight surface contacts by z

$$G(t,q;\mathbf{z}) = rac{1}{1-rac{t\mathbf{z}}{1-rac{qt}{1-rac{q^2t}{1-\dots}}}}$$

• Equivalently

$$G(t,q;z) = \frac{1}{1-tzG(qt,q)}$$

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Bulk pressure

• Density of contacts $\rho(q)$ is related to singularity $t_c(q; z)$

$$\rho(q) = -\left. \frac{\partial \log t_c(q; z)}{\partial \log z} \right|_{z=1}$$

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Directed Walk Models Dyck paths Adsorbing Dyck paths Area-weighted Dyck paths

Bulk pressure

• Density of contacts $\rho(q)$ is related to singularity $t_c(q; z)$

$$\rho(q) = -\left. \frac{\partial \log t_c(q; z)}{\partial \log z} \right|_{z=1}$$

• We find for the pressure P(q)

$$P(q) = -\log(1-
ho(q)) + \log q$$

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Bulk pressure

Bulk pressure for n = 10 to 80 (left) and in the TDL (right)



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Pressure Profiles

Pressure profiles for q = 0.98 (left), 1.00 (center), and 1.02 (right)



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Pressure Profiles

Pressure profiles for q = 0.98 (left), 1.00 (center), and 1.02 (right)



Rate of convergence: ρ^n (left), $n^{-1/2}$ (center), and ρ^{n^2} (right)

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Outline



2 Exactly Solvable Models



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Conclusion

• Entropy-driven pressure of polymers

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Conclusion

- Entropy-driven pressure of polymers
- Gaussian Chain and Self-Avoiding Walk

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Conclusion

- Entropy-driven pressure of polymers
- Gaussian Chain and Self-Avoiding Walk
- Exactly solvable directed walk model with
 - contacts
 - area

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Conclusion

- Entropy-driven pressure of polymers
- Gaussian Chain and Self-Avoiding Walk
- Exactly solvable directed walk model with
 - contacts
 - area

Simple lattice models still manage to give useful physical insight!

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