## Area-weighed Dyck paths as vesicle models an approach via *q*-deformed algebraic and linear functional equations

#### Thomas Prellberg joint work with Aleksander L Owczarek

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# **Topic Outline**

### Physical Motivation

#### 2 Mathematical Motivation

- q-deformed algebraic equation
- q-deformed linear functional equation

### Solving the Functional Equations

- q-deformed algebraic equation
- q-deformed linear functional equation

### 4 Back to Physics

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# Outline

### 1 Physical Motivation

#### Mathematical Motivation

- q-deformed algebraic equation
- q-deformed linear functional equation

#### 3 Solving the Functional Equations

- q-deformed algebraic equation
- q-deformed linear functional equation

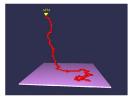
#### Back to Physics

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# **Physical Motivation**

Force-induced desorption (optical tweezers)

• Pulling a sticky polymer off a surface

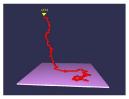


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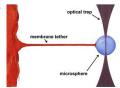
# **Physical Motivation**

Force-induced desorption (optical tweezers)

• Pulling a sticky polymer off a surface

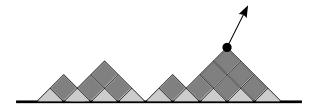


• Pulling on a membrane attached to a surface



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# Toy model: Dyck path



- 18 = 2n steps (*n* half length)
- 11 = m area (*m* rank function)
- 4 = h height (*h* length of final descent)

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q-deformed algebraic equation q-deformed linear functional equation

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### Back to Physics

q-deformed algebraic equation q-deformed linear functional equation

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# Mathematical Motivation

Compare two models of solving for the generating function

- Algebraic equation
- Linear functional equation in a "catalytic variable"

and their *q*-deformations

*q*-deformed algebraic equation *q*-deformed linear functional equation

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# Mathematical Motivation

Compare two models of solving for the generating function

- Algebraic equation
- Linear functional equation in a "catalytic variable"

and their *q*-deformations

#### Generating function

$$G(t,q,\lambda) = \sum_{\pi \text{ Dyck path}} t^{n(\pi)} q^{m(\pi)} \lambda^{h(\pi)}$$

*q*-deformed algebraic equation *q*-deformed linear functional equation

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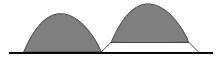
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## q-algebraic equation

Unique combinatorial decomposition of a Dyck path



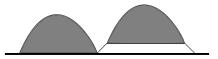
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## q-algebraic equation

Unique combinatorial decomposition of a Dyck path



Functional equation

$$G(t,q,\lambda) = 1 + \underbrace{G(t,q,1)}_{(\mathrm{a})} t \underbrace{G(qt,q,\lambda)}_{(\mathrm{b})} \lambda$$

(a) left Dyck path does not contribute to final descent: G(t, q, 1)
(b) raised right Dyck path increases area: G(qt, q, λ)

q-deformed algebraic equation q-deformed linear functional equation

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#### Back to Physics

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## q-deformed linear functional equation

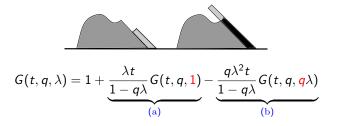


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### q-deformed linear functional equation

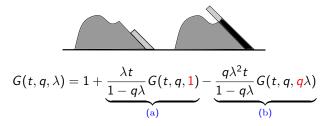


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## q-deformed linear functional equation

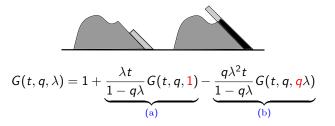


(a) add hooks irrespective of height

$$+G(t,q,1) \times (\lambda t + q\lambda^2 t + q^2\lambda^3 t + \ldots)$$

*q*-deformed algebraic equation *q*-deformed linear functional equation

## q-deformed linear functional equation



(a) add hooks irrespective of height

$$+G(t,q,1) \times (\lambda t + q\lambda^2 t + q^2\lambda^3 t + \ldots)$$

#### (b) correct for overcounting

$$-G(t,q,q\lambda) imes (q\lambda^2 t + q^2\lambda^3 t + q^3\lambda^4 t + \ldots)$$

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q-deformed algebraic equation q-deformed linear functional equation

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### algebraic equation

Functional equation

$$G(t,q,\lambda) = 1 + \lambda t G(t,q,1) G(qt,q,\lambda)$$

Thomas Prellberg joint work with Aleksander L Owczarek Area-weighed Dyck paths as vesicle models

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### algebraic equation

Functional equation

$$G(t,q,\lambda) = 1 + \lambda t G(t,q,1) G(qt,q,\lambda)$$

• q = 1 and  $\lambda = 1$ : quadratic equation

$$G(t,1,1) = rac{1-\sqrt{1-4t}}{2t} = rac{2}{1+\sqrt{1-4t}}$$

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$$G(t,1,1) = rac{1-\sqrt{1-4t}}{2t} = rac{2}{1+\sqrt{1-4t}}$$

• q = 1: back-substitution of G(t, 1, 1) gives

$$G(t,1,\lambda)=rac{2}{2-\lambda+\lambda\sqrt{1-4t}}=\sum_{l=0}^{\infty}\lambda^lt^lG(t,1,1)^l$$

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### algebraic equation

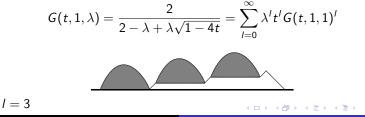
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### q-deformed algebraic equation

•  $q \neq 1$  and  $\lambda = 1$ : non-linear q-difference equation

 $G(t,q,1) = 1 + \lambda t G(t,q,1) G(qt,q,1)$ 

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### q-deformed algebraic equation

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$$G(t,q,1) = 1 + \lambda t G(t,q,1) G(qt,q,1)$$

make Ansatz

$$G(t,q,1)=rac{H(qt,q)}{H(t,q)}$$

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• the resulting q-difference equation is linear

$$H(qt,q) = H(t,q) + tH(q^2t,q)$$

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• the resulting q-difference equation is linear

$$H(qt,q) = H(t,q) + tH(q^2t,q)$$

standard methods give

$$H(t,q) = \sum_{k=0}^{\infty} \frac{(-t)^k q^{k(k-1)}}{(q;q)_k}$$

where  $(t; q)_k = \prod_{j=0}^{k-1} (1 - tq^j)$ 

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## q-deformed algebraic equation

General solution of

$$G(t,q,\lambda) = 1 + \lambda t G(t,q,1) G(qt,q,\lambda)$$

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iterating gives

$$G(t,q,\lambda) = 1 + \lambda t G(t,q,1) \left(1 + \lambda q t G(qt,q,1)(1 + \ldots)\right)$$

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• we find explicitly

$$G(t,q,\lambda) = \sum_{l=0}^{\infty} \prod_{k=0}^{l-1} \left( \lambda t q^k G(q^k t, 1, 1) \right)$$

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• combinatorial interpretation (with the power of hindsight)



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### First General Solution

#### We rewrite

$$G(t,q,\lambda) = \sum_{l=0}^{\infty} \prod_{k=0}^{l-1} \left( \lambda t q^k G(q^k t, 1, 1) \right) = \sum_{l=0}^{\infty} \lambda^l t^l q^{\binom{l}{2}} \frac{H(q^l t, q)}{H(t,q)}$$

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### First General Solution

#### We rewrite

$$G(t,q,\lambda) = \sum_{l=0}^{\infty} \prod_{k=0}^{l-1} \left( \lambda t q^{k} G(q^{k}t,1,1) \right) = \sum_{l=0}^{\infty} \lambda^{l} t^{l} q^{\binom{l}{2}} \frac{H(q^{l}t,q)}{H(t,q)}$$

#### and find explicitly

$$G(t,q,\lambda) = \sum_{l=0}^{\infty} \lambda^{l} t^{l} q^{\binom{l}{2}} \frac{\sum_{k=0}^{\infty} \frac{(-q^{l}t)^{k} q^{k(k-1)}}{(q;q)_{k}}}{\sum_{k=0}^{\infty} \frac{(-t)^{k} q^{k(k-1)}}{(q;q)_{k}}}$$

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q-deformed algebraic equation q-deformed linear functional equation

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q-deformed algebraic equation q-deformed linear functional equation

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## linear functional equation

Functional equation

$$G(t,q,\lambda) = 1 + rac{\lambda t}{1-q\lambda}G(t,q,\mathbf{1}) - rac{q\lambda^2 t}{1-q\lambda}G(t,q,\mathbf{q}\lambda)$$

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• q=1: linear functional equation in the "catalytic variable"  $\lambda$ 

$$G(t,1,\lambda) = 1 + rac{\lambda t}{1-\lambda}G(t,1,1) - rac{\lambda^2 t}{1-\lambda}G(t,1,\lambda)$$

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• setting  $\lambda = 1$  does not work!

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## linear functional equation

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$$G(t,1,\lambda) = 1 + rac{\lambda t}{1-\lambda}G(t,1,1) - rac{\lambda^2 t}{1-\lambda}G(t,1,\lambda)$$

• setting  $\lambda = 1$  does not work! "Kernel method": Rewrite

$$\mathcal{K}(t,\lambda)\mathcal{G}(t,1,\lambda) = 1 + rac{\lambda t}{1-\lambda}\mathcal{G}(t,1,1)$$

with Kernel

$$K(t,\lambda) = 1 + rac{\lambda^2 t}{1-\lambda t}$$

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## Kernel method

Solving

$$K(t,\lambda)G(t,1,\lambda) = 1 + rac{\lambda t}{1-\lambda}G(t,1,1)$$

with Kernel

$$\mathcal{K}(t,\lambda) = 1 + rac{\lambda^2 t}{1-\lambda t}$$

*q*-deformed algebraic equation *q*-deformed linear functional equation

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$$\mathcal{K}(t,\lambda) = 1 + rac{\lambda^2 t}{1-\lambda t}$$

• LHS vanishes for some value  $\lambda = \lambda_0$  such that  $K(t, \lambda_0) = 0$ 

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### Kernel method

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LHS vanishes for some value λ = λ<sub>0</sub> such that K(t, λ<sub>0</sub>) = 0
RHS gives

$$G(t,1,1)=rac{\lambda_0-1}{1-\lambda_0 t} \hspace{0.3cm} ext{where} \hspace{0.3cm} \lambda_0=rac{1-\sqrt{1-4t}}{2t}$$

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we find

$$G(t,1,\lambda) = rac{1+rac{\lambda t}{1-\lambda}rac{\lambda_0 t-1}{\lambda_0 t}}{K(t,\lambda)}$$

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we find

$$G(t,1,\lambda) = rac{1+rac{\lambda t}{1-\lambda}rac{\lambda_0 t-1}{\lambda_0 t}}{K(t,\lambda)}$$

• eventually we recover the earlier solution

q-deformed algebraic equation q-deformed linear functional equation

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### q-deformed linear functional equation

Now consider

$$G(t,q,\lambda) = 1 + rac{\lambda t}{1-q\lambda}G(t,q,\mathbf{1}) - rac{q\lambda^2 t}{1-q\lambda}G(t,q,q\lambda)$$

for  $q \neq 1$ 

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### q-deformed linear functional equation

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for  $q \neq 1$ 

• mimic the Kernel method: rewrite

$$\left(1+rac{q\lambda^2t}{1-q\lambda}\mathcal{Q}
ight)G(t,q,\lambda)=1+rac{\lambda t}{1-q\lambda}G(t,q,1)$$

with an operator

$$(\mathcal{Q}G)(t,q,\lambda) = G(t,q,q\lambda)$$

q-deformed algebraic equation q-deformed linear functional equation

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$$G(t,q,\lambda) = 1 + rac{\lambda t}{1-q\lambda}G(t,q,\mathbf{1}) - rac{q\lambda^2 t}{1-q\lambda}G(t,q,\mathbf{q}\lambda)$$

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with an operator

$$(\mathcal{Q}G)(t,q,\lambda) = G(t,q,q\lambda)$$

• we obtain formally

$$G(t,q,\lambda) = \left(1 + \frac{q\lambda^2 t}{1-q\lambda}\mathcal{Q}\right)^{-1} \left(1 + \frac{\lambda t}{1-q\lambda}G(t,q,1)\right)$$

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### q-deformed linear functional equation

now expand

$$G(t,q,\lambda) = \left(1+rac{q\lambda^2 t}{1-q\lambda}\mathcal{Q}
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q-deformed algebraic equation q-deformed linear functional equation

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now expand

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we find

$$G(t,q,\lambda) = \sum_{k=0}^{\infty} \left( -rac{q\lambda^2 t}{1-q\lambda} \mathcal{Q} 
ight)^k \left( 1 + rac{\lambda t}{1-q\lambda} G(t,q,1) 
ight)$$

q-deformed algebraic equation q-deformed linear functional equation

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### q-deformed linear functional equation

now expand

$$G(t,q,\lambda) = \left(1 + rac{q\lambda^2 t}{1-q\lambda}\mathcal{Q}
ight)^{-1} \left(1 + rac{\lambda t}{1-q\lambda}G(t,q,1)
ight)$$

we find

$$\begin{split} G(t,q,\lambda) &= \sum_{k=0}^{\infty} \left( -\frac{q\lambda^2 t}{1-q\lambda} \mathcal{Q} \right)^k \left( 1 + \frac{\lambda t}{1-q\lambda} G(t,q,1) \right) \\ &= \sum_{k=0}^{\infty} \frac{(-\lambda^2 t)^k q^{k^2}}{(q\lambda;q)_k} \left( 1 + \frac{q^k \lambda t}{1-q^{k+1}\lambda} G(t,q,1) \right) \end{split}$$

q-deformed algebraic equation q-deformed linear functional equation

### q-deformed linear functional equation

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ight) \end{aligned}$$

• Letting  $\lambda = 1$  this simplifies to

$$G(t,q,1)=H(qt,q)-(H(t,q)-1)G(t,q,1)$$

and we recover

$$G(t,q,1) = H(qt,q)/H(t,q)$$

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q-deformed algebraic equation q-deformed linear functional equation

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### Second General Solution

#### We find explicitly

$$G(t,q,\lambda) = \sum_{k=0}^{\infty} \frac{(-q\lambda^2 t)^k q^{k(k-1)}}{(q\lambda;q)_k} - \frac{1}{\lambda} \sum_{k=1}^{\infty} \frac{(-\lambda^2 t)^k q^{k(k-1)}}{(q\lambda;q)_k} \frac{H(qt,q)}{H(t,q)}$$

q-deformed algebraic equation q-deformed linear functional equation

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• no obvious combinatorial interpretation (yet)

q-deformed algebraic equation q-deformed linear functional equation

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### Second General Solution

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- no obvious combinatorial interpretation (yet)
- a clearly very different solution from

$$G(t,q,\lambda) = \sum_{l=0}^{\infty} \lambda^l t^l q^{\binom{l}{2}} \frac{H(q^l t,q)}{H(t,q)}$$

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# Why bother?

- Compare two fundamentally different ways of setting up and solving functional equations
- Algebraic decomposition does not always work
- The Kernel method approach is more general

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# Why bother?

- Compare two fundamentally different ways of setting up and solving functional equations
- Algebraic decomposition does not always work
- The Kernel method approach is more general
- However, there are cases when the Kernel method is fiendishly difficult to apply
- The *q*-deformation might actually make the functional equations easier to solve
- Work in progress ...

# Outline

### Physical Motivation

### Mathematical Motivation

- q-deformed algebraic equation
- q-deformed linear functional equation

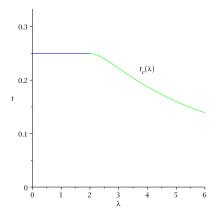
#### 3 Solving the Functional Equations

- q-deformed algebraic equation
- q-deformed linear functional equation

### 4 Back to Physics

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### The phase diagram for q = 1

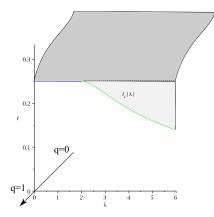


#### • Phase transition at $\lambda = 2$

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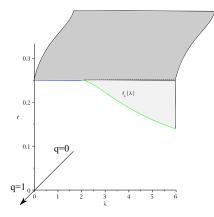
### The phase diagram for general q



•  $t_c(\lambda, q)$  independent of  $\lambda$  for q < 1

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## The phase diagram for general q



- $t_c(\lambda, q)$  independent of  $\lambda$  for q < 1
- Free energy jumps at q = 1 for  $\lambda > 2$

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