

Efficient designs for two-colour microarray experiments

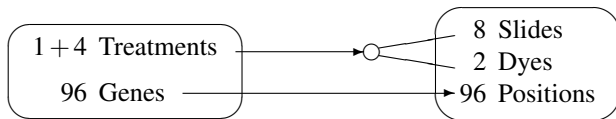
R. A. Bailey



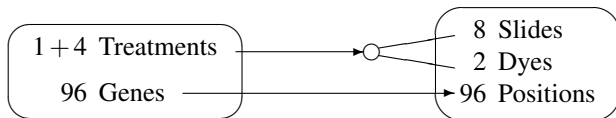
`r.a.bailey@qmul.ac.uk`

International Biometric Conference,
Dublin, July 2008

A small microarray experiment

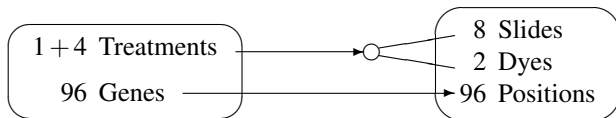


A small microarray experiment



- There is 1 'control' treatment (labelled 0) and 4 other treatments.

A small microarray experiment



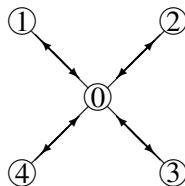
- ▶ There is 1 'control' treatment (labelled 0) and 4 other treatments.
- ▶ ○ shows that we need to know a specific (non-orthogonal) design for the allocation of the treatments to the dye-slide combinations, such as

		slides							
		1	2	3	4	5	6	7	8
red		0	1	0	2	0	3	0	4
green		1	0	2	0	3	0	4	0

Representation of the design as an oriented graph

Treatments are vertices; slides are edges, oriented from green to red.

	slides							
	1	2	3	4	5	6	7	8
red	0	1	0	2	0	3	0	4
green	1	0	2	0	3	0	4	0

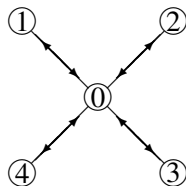


double
reference

Representation of the design as an oriented graph

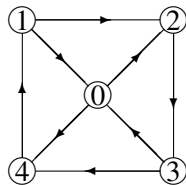
Treatments are vertices; slides are edges, oriented from green to red.

	slides							
	1	2	3	4	5	6	7	8
red	0	1	0	2	0	3	0	4
green	1	0	2	0	3	0	4	0



double
reference

	slides							
	1	2	3	4	5	6	7	8
red	0	2	0	4	2	3	4	1
green	1	0	3	0	1	2	3	4

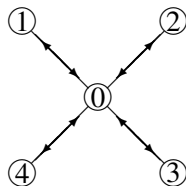


wheel

Representation of the design as an oriented graph

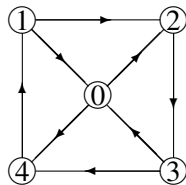
Treatments are vertices; slides are edges, oriented from green to red.

	slides							
	1	2	3	4	5	6	7	8
red	0	1	0	2	0	3	0	4
green	1	0	2	0	3	0	4	0



double
reference

	slides							
	1	2	3	4	5	6	7	8
red	0	2	0	4	2	3	4	1
green	1	0	3	0	1	2	3	4



wheel

Which is better?

Model

t treatments

b slides (call these “blocks”)

2 dyes

Model

t treatments b slides (call these “blocks”) 2 dyes

Assume that the logarithm of the intensity of treatment i coloured with dye l in block k has expected value

$$\tau_i + \beta_k + \delta_l$$

and variance σ^2 , independent of all other responses.

t treatments b slides (call these “blocks”) 2 dyes

Assume that the logarithm of the intensity of treatment i coloured with dye l in block k has expected value

$$\tau_i + \beta_k + \delta_l$$

and variance σ^2 , independent of all other responses.

To estimate all the $\tau_i - \tau_j$, we need $b \geq t - 1$.

Optimality criteria

If there are just 2 treatments, we want V_{12} , the variance of the estimator of $\tau_1 - \tau_2$, to be small and we want the confidence interval I_{12} for $\tau_1 - \tau_2$ to be small.

Optimality criteria

If there are just 2 treatments, we want V_{12} , the variance of the estimator of $\tau_1 - \tau_2$, to be small and we want the confidence interval I_{12} for $\tau_1 - \tau_2$ to be small.

I_{12} is proportional to $\sqrt{V_{12}}$.

Optimality criteria

If there are just 2 treatments, we want V_{12} , the variance of the estimator of $\tau_1 - \tau_2$, to be small

and we want the confidence interval I_{12} for $\tau_1 - \tau_2$ to be small.

I_{12} is proportional to $\sqrt{V_{12}}$.

In general, a design is **A-optimal** if it minimizes the sum of the variances of the estimators of the pairwise differences;

a design is **D-optimal** if it minimizes the volume of the confidence ellipsoid for the vector (τ_1, \dots, τ_t) subject to $\sum \tau_i = 0$.

Optimality criteria

If there are just 2 treatments, we want V_{12} , the variance of the estimator of $\tau_1 - \tau_2$, to be small

and we want the confidence interval I_{12} for $\tau_1 - \tau_2$ to be small.

I_{12} is proportional to $\sqrt{V_{12}}$.

In general, a design is **A-optimal** if it minimizes the sum of the variances of the estimators of the pairwise differences;

a design is **D-optimal** if it minimizes the volume of the confidence ellipsoid for the vector (τ_1, \dots, τ_t) subject to $\sum \tau_i = 0$.

If $t = 2$ then A-optimal = D-optimal.

Temporarily ignore the dyes

We will come back to them later.

Experience with block designs of many sizes

- ▶ Designs which are good on the A-criterion are also good on the D-criterion ...

Experience with block designs of many sizes

- ▶ Designs which are good on the A-criterion are also good on the D-criterion ...
- ▶ ... and vice versa.

Experience with block designs of many sizes

- ▶ Designs which are good on the A-criterion are also good on the D-criterion ...
- ▶ ... and vice versa.
- ▶ The best designs have equal replication.

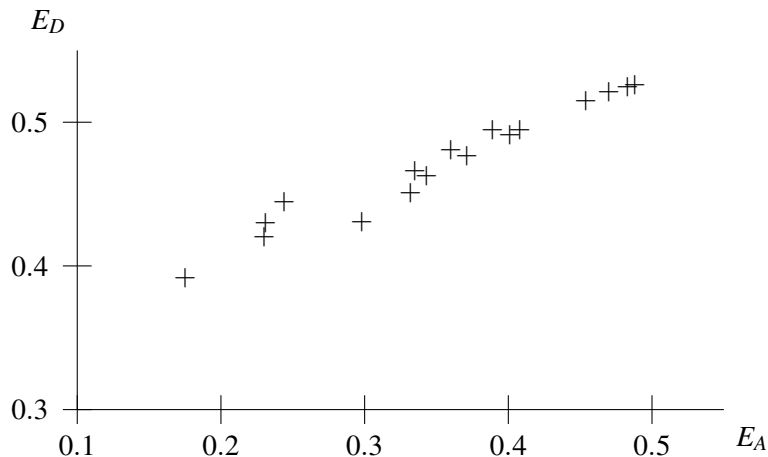
Experience with block designs of many sizes

- ▶ Designs which are good on the A-criterion are also good on the D-criterion ...
- ▶ ... and vice versa.
- ▶ The best designs have equal replication.
- ▶ The best designs are symmetric.

Experience with block designs of many sizes

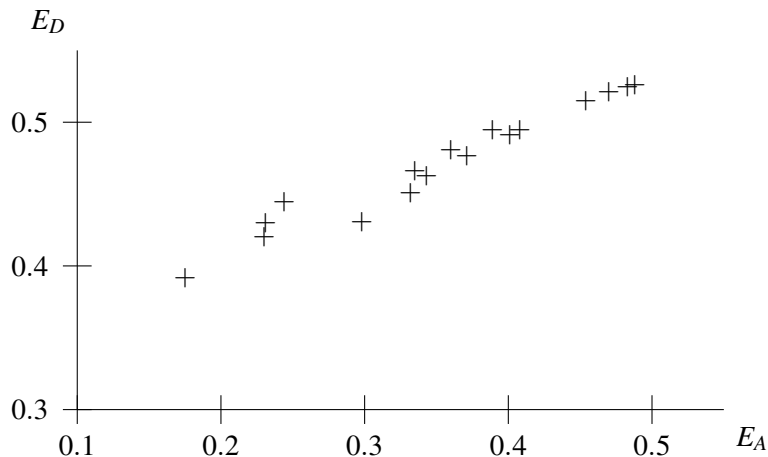
- ▶ Designs which are good on the A-criterion are also good on the D-criterion ...
- ▶ ... and vice versa.
- ▶ The best designs have equal replication.
- ▶ The best designs are symmetric.
- ▶ V_{ij} , the variance of the estimator of $\tau_i - \tau_j$, is usually smaller if the distance between vertices i and j in the graph is smaller.

Typical behaviour of the optimality criteria



Optimality criteria for all connected equireplicate designs with 8 treatments in 12 blocks of size 2:

Typical behaviour of the optimality criteria



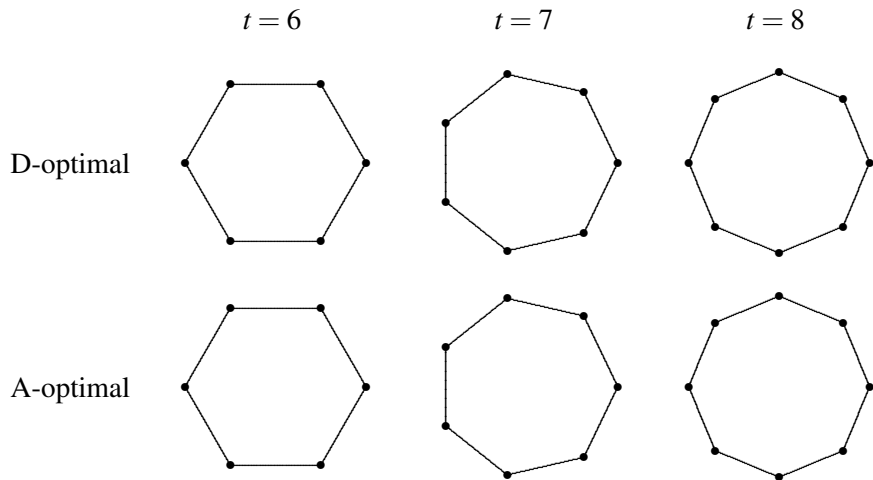
Optimality criteria for all connected equireplicate designs with 8 treatments in 12 blocks of size 2: both criteria are normalized to lie between 0 (worst, for designs where not everything can be estimated) and 1 (best, for designs consisting a single large block)

What happens when $b = t$?

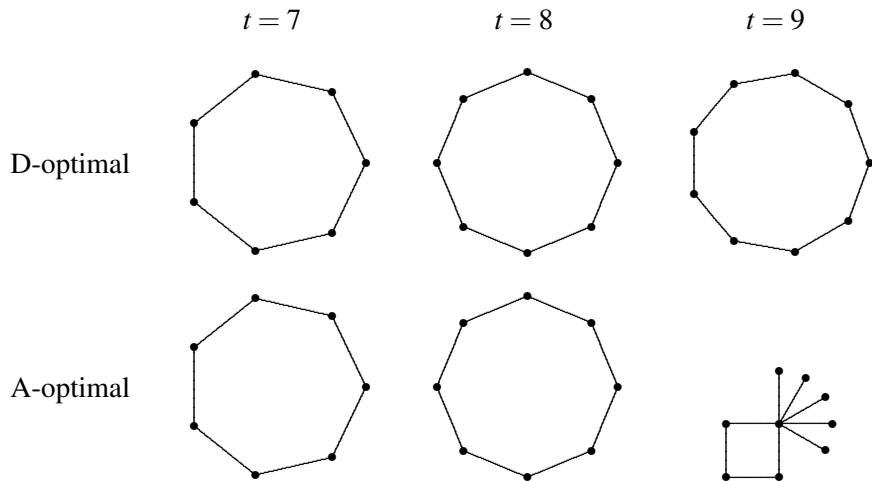
Computer investigation by

- ▶ Jones and Eccleston (1980)
- ▶ Kerr and Churchill (2001)
- ▶ Wit, Nobile and Khanin (2005)
- ▶ Ceraudo (2005).

Optimal designs when $b = t$



Optimal designs when $b = t$



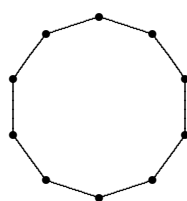
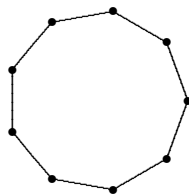
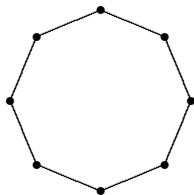
Optimal designs when $b = t$

$t = 8$

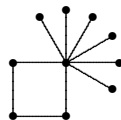
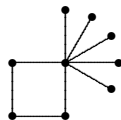
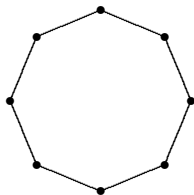
$t = 9$

$t = 10$

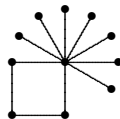
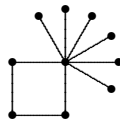
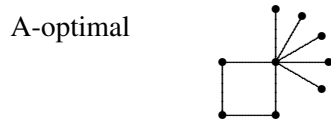
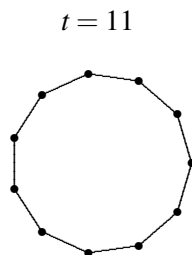
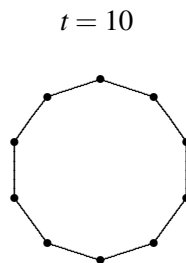
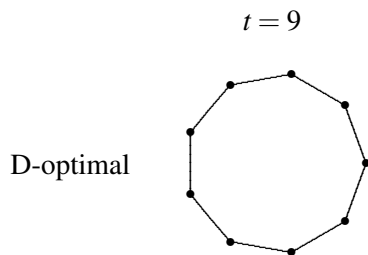
D-optimal



A-optimal



Optimal designs when $b = t$



D-optimality

Cheng (1978), after Gaffke (1978), after Kirchhoff (1847):

$$E_D = \frac{(t \times \text{number of spanning trees})^{1/(t-1)}}{2\bar{r}}$$

D-optimality

Cheng (1978), after Gaffke (1978), after Kirchhoff (1847):

$$E_D = \frac{(t \times \text{number of spanning trees})^{1/(t-1)}}{2\bar{r}}$$

number of spanning trees =

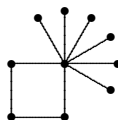
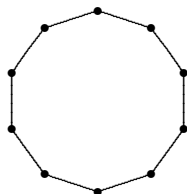
number of ways of removing $b - t + 1$ edges without disconnecting the graph, (which is easy to calculate by hand when $b - t$ is small)

D-optimality

Cheng (1978), after Gaffke (1978), after Kirchhoff (1847):

$$E_D = \frac{(t \times \text{number of spanning trees})^{1/(t-1)}}{2\bar{r}}$$

number of spanning trees =
number of ways of removing $b - t + 1$ edges without disconnecting
the graph, (which is easy to calculate by hand when $b - t$ is small)

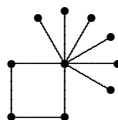
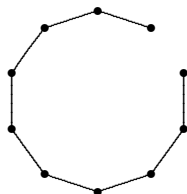


D-optimality

Cheng (1978), after Gaffke (1978), after Kirchhoff (1847):

$$E_D = \frac{(t \times \text{number of spanning trees})^{1/(t-1)}}{2\bar{r}}$$

number of spanning trees =
number of ways of removing $b - t + 1$ edges without disconnecting
the graph, (which is easy to calculate by hand when $b - t$ is small)

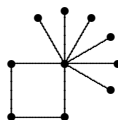
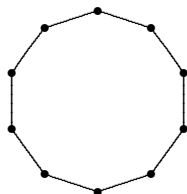


D-optimality

Cheng (1978), after Gaffke (1978), after Kirchhoff (1847):

$$E_D = \frac{(t \times \text{number of spanning trees})^{1/(t-1)}}{2\bar{r}}$$

number of spanning trees =
number of ways of removing $b - t + 1$ edges without disconnecting
the graph, (which is easy to calculate by hand when $b - t$ is small)

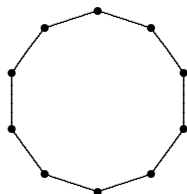


D-optimality

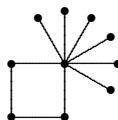
Cheng (1978), after Gaffke (1978), after Kirchhoff (1847):

$$E_D = \frac{(t \times \text{number of spanning trees})^{1/(t-1)}}{2\bar{r}}$$

number of spanning trees =
number of ways of removing $b - t + 1$ edges without disconnecting the graph, (which is easy to calculate by hand when $b - t$ is small)



10 spanning trees

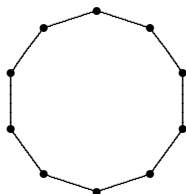


D-optimality

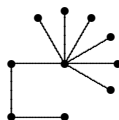
Cheng (1978), after Gaffke (1978), after Kirchhoff (1847):

$$E_D = \frac{(t \times \text{number of spanning trees})^{1/(t-1)}}{2\bar{r}}$$

number of spanning trees =
number of ways of removing $b - t + 1$ edges without disconnecting
the graph, (which is easy to calculate by hand when $b - t$ is small)



10 spanning trees



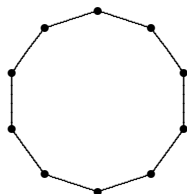
D-optimality

Cheng (1978), after Gaffke (1978), after Kirchhoff (1847):

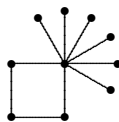
$$E_D = \frac{(t \times \text{number of spanning trees})^{1/(t-1)}}{2\bar{r}}$$

number of spanning trees =

number of ways of removing $b - t + 1$ edges without disconnecting the graph, (which is easy to calculate by hand when $b - t$ is small)



10 spanning trees



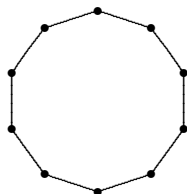
4 spanning trees

D-optimality

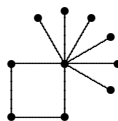
Cheng (1978), after Gaffke (1978), after Kirchhoff (1847):

$$E_D = \frac{(t \times \text{number of spanning trees})^{1/(t-1)}}{2\bar{r}}$$

number of spanning trees =
number of ways of removing $b - t + 1$ edges without disconnecting the graph, (which is easy to calculate by hand when $b - t$ is small)



10 spanning trees

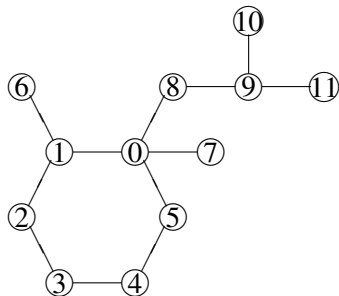


4 spanning trees

The loop design is uniquely D-optimal when $b = t$.

A-optimality

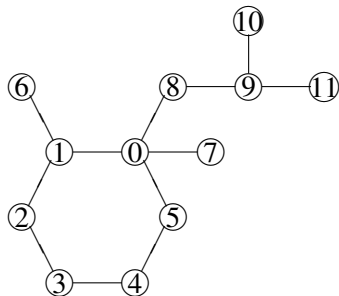
If $b = t$, the graph contains a single circuit.



A-optimality

If $b = t$, the graph contains a single circuit.

Let $V_{ij} =$ variance of estimator of $\tau_i - \tau_j$.

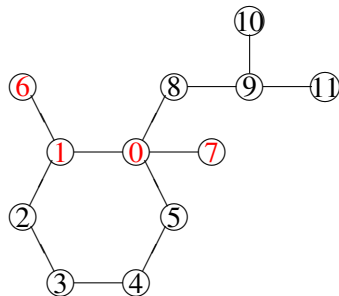


A-optimality

If $b = t$, the graph contains a single circuit.

Let V_{ij} = variance of estimator of $\tau_i - \tau_j$.

$$V_{67} = V_{61} + V_{10} + V_{07} = V_{10} + 4\sigma^2$$



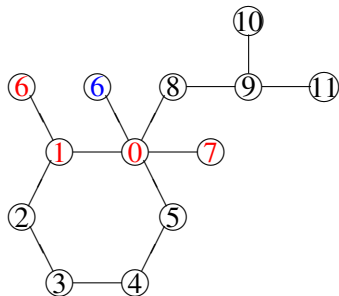
A-optimality

If $b = t$, the graph contains a single circuit.

Let V_{ij} = variance of estimator of $\tau_i - \tau_j$.

$$V_{67} = V_{61} + V_{10} + V_{07} = V_{10} + 4\sigma^2$$

$$V_{67} = V_{60} + V_{07} = 4\sigma^2$$

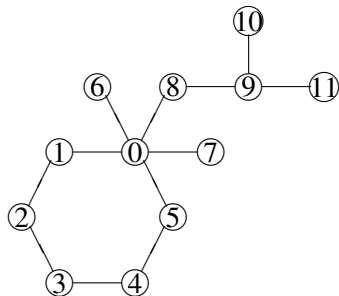


A-optimality

If $b = t$, the graph contains a single circuit.

Let V_{ij} = variance of estimator of $\tau_i - \tau_j$.

$$V_{67} = V_{60} + V_{07} = 4\sigma^2$$

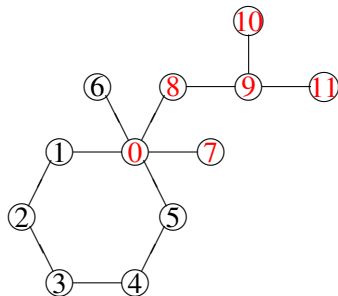


A-optimality

If $b = t$, the graph contains a single circuit.

Let V_{ij} = variance of estimator of $\tau_i - \tau_j$.

$$V_{97} = V_{98} + V_{80} + V_{07} = V_{80} + 4\sigma^2$$



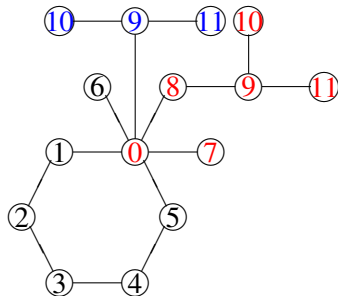
A-optimality

If $b = t$, the graph contains a single circuit.

Let V_{ij} = variance of estimator of $\tau_i - \tau_j$.

$$V_{97} = V_{98} + V_{80} + V_{07} = V_{80} + 4\sigma^2$$

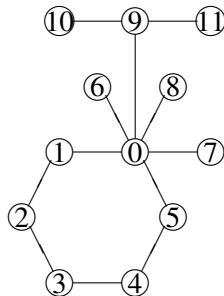
$$V_{97} = V_{90} + V_{07} = 4\sigma^2$$



A-optimality

If $b = t$, the graph contains a single circuit.

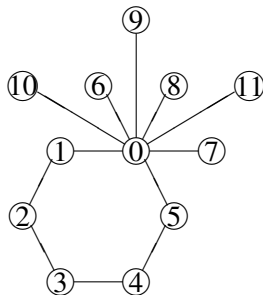
Let $V_{ij} =$ variance of estimator of $\tau_i - \tau_j$.



A-optimality

If $b = t$, the graph contains a single circuit.

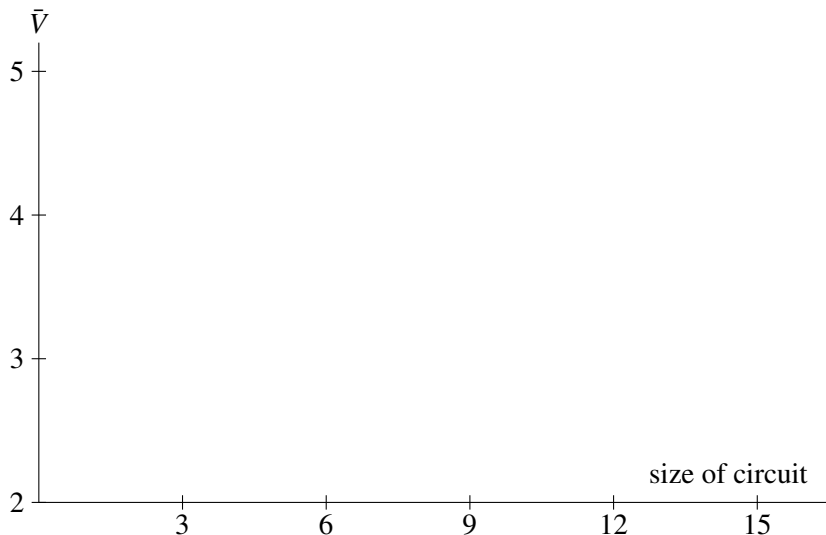
Let $V_{ij} =$ variance of estimator of $\tau_i - \tau_j$.



For a given size of circuit, the total variance is minimized when everything outside the circuit is attached to the same vertex of the circuit.

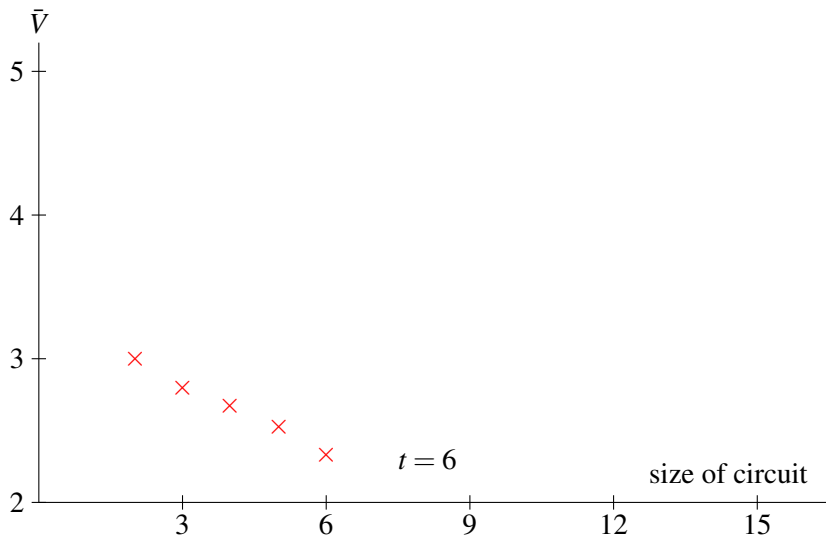
Leaves attached to the same vertex of the circuit

Average pairwise variance is a cubic function of the size of the circuit.



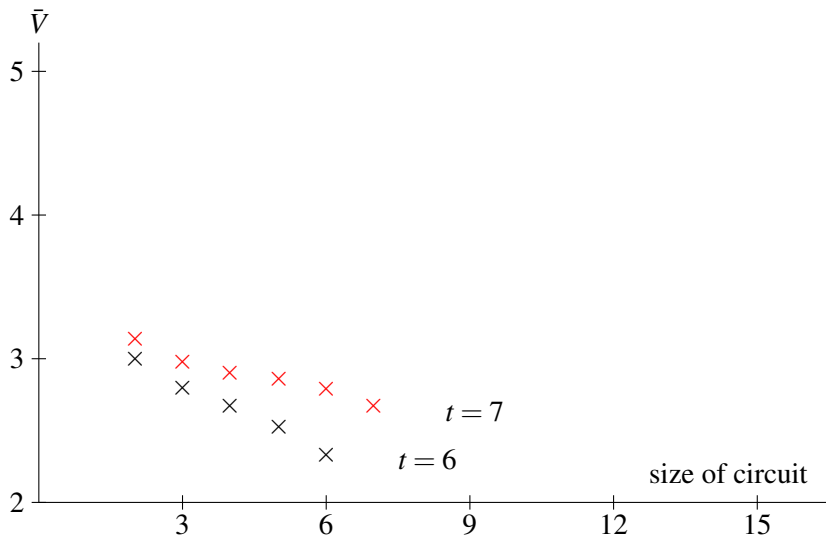
Leaves attached to the same vertex of the circuit

Average pairwise variance is a cubic function of the size of the circuit.



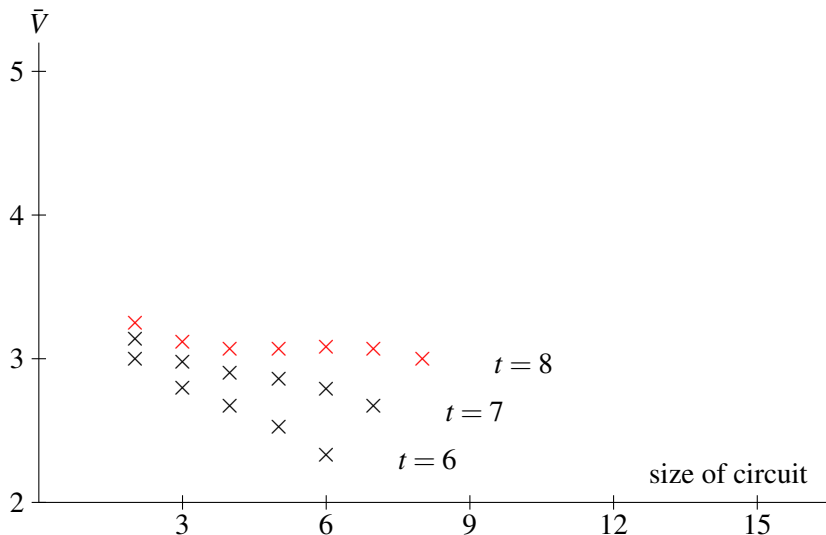
Leaves attached to the same vertex of the circuit

Average pairwise variance is a cubic function of the size of the circuit.



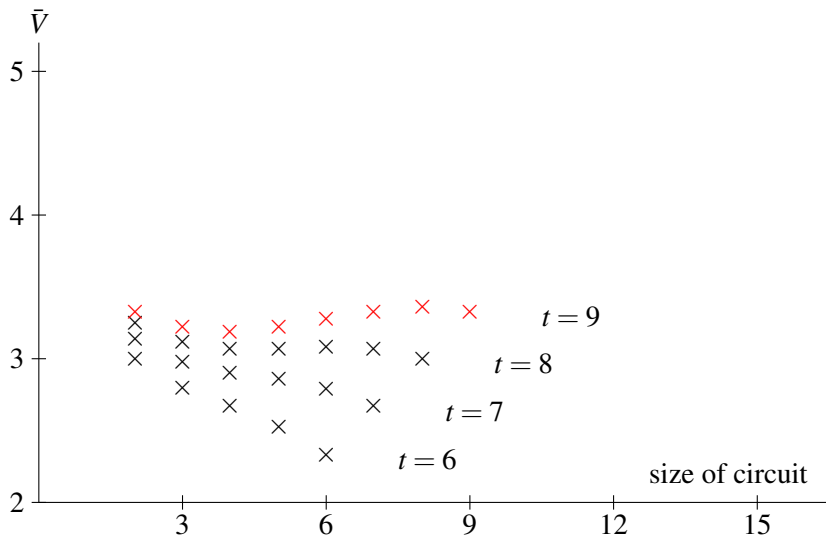
Leaves attached to the same vertex of the circuit

Average pairwise variance is a cubic function of the size of the circuit.



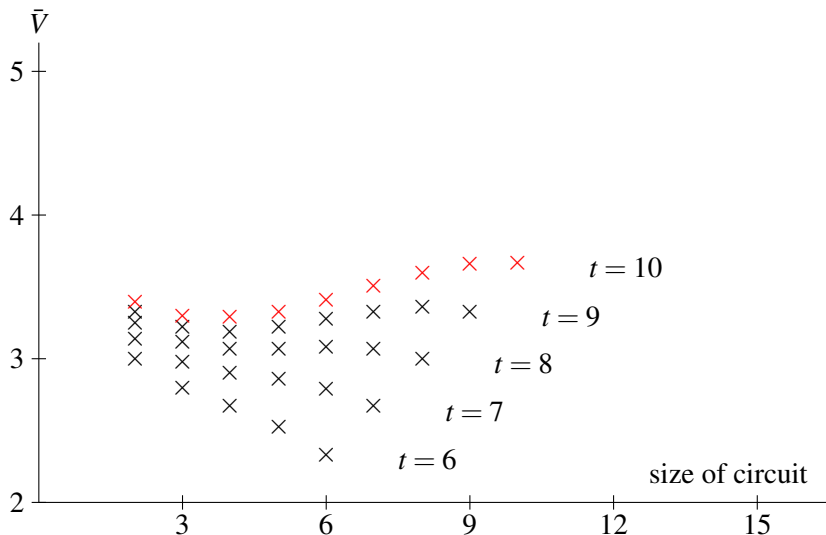
Leaves attached to the same vertex of the circuit

Average pairwise variance is a cubic function of the size of the circuit.



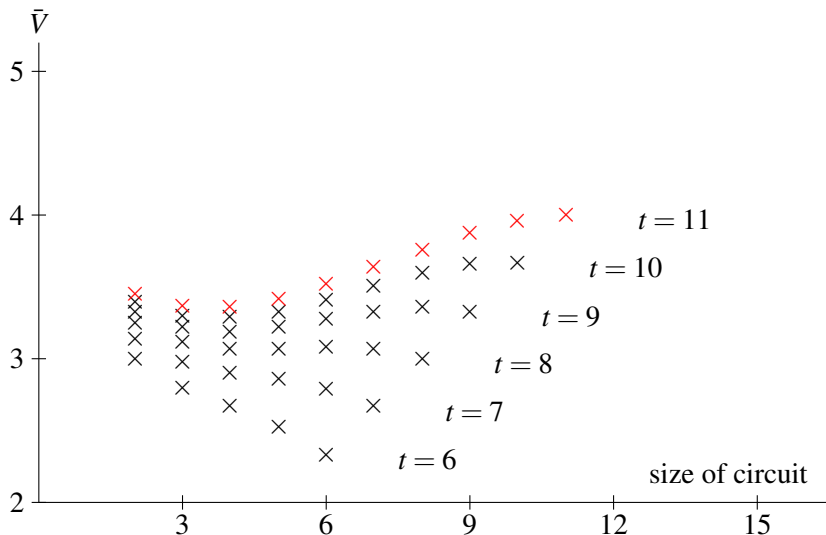
Leaves attached to the same vertex of the circuit

Average pairwise variance is a cubic function of the size of the circuit.



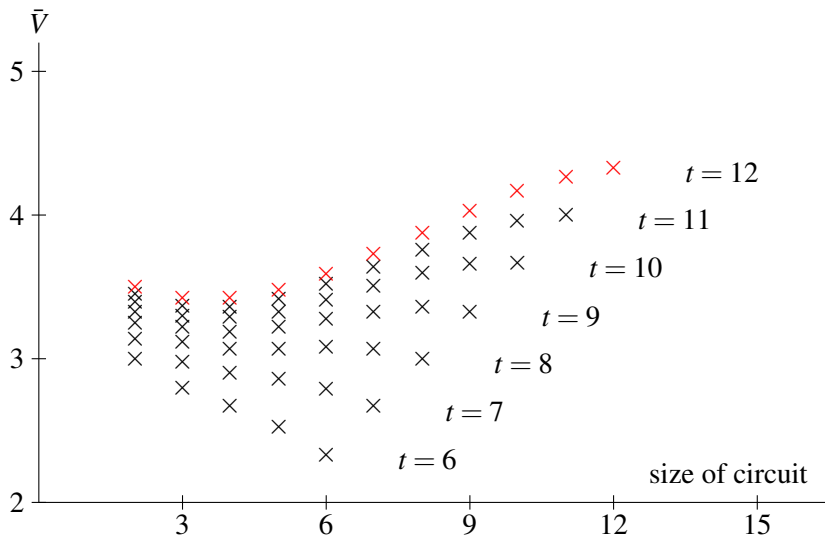
Leaves attached to the same vertex of the circuit

Average pairwise variance is a cubic function of the size of the circuit.



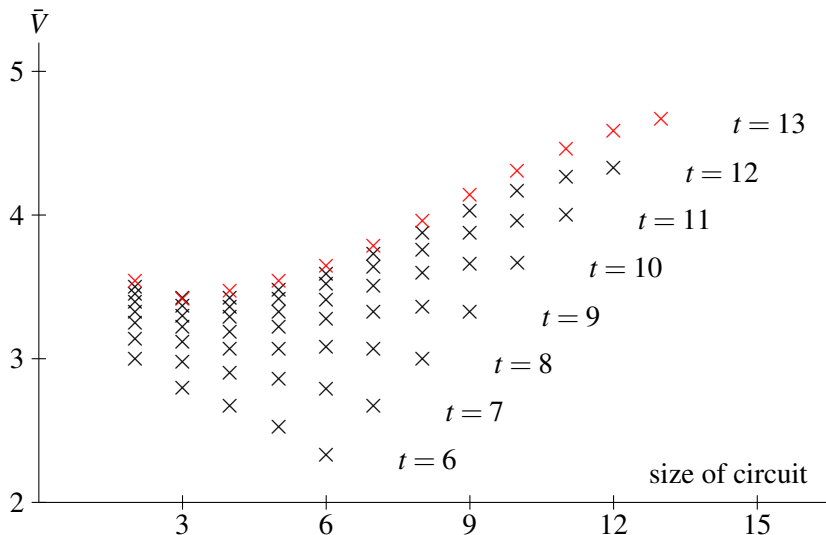
Leaves attached to the same vertex of the circuit

Average pairwise variance is a cubic function of the size of the circuit.



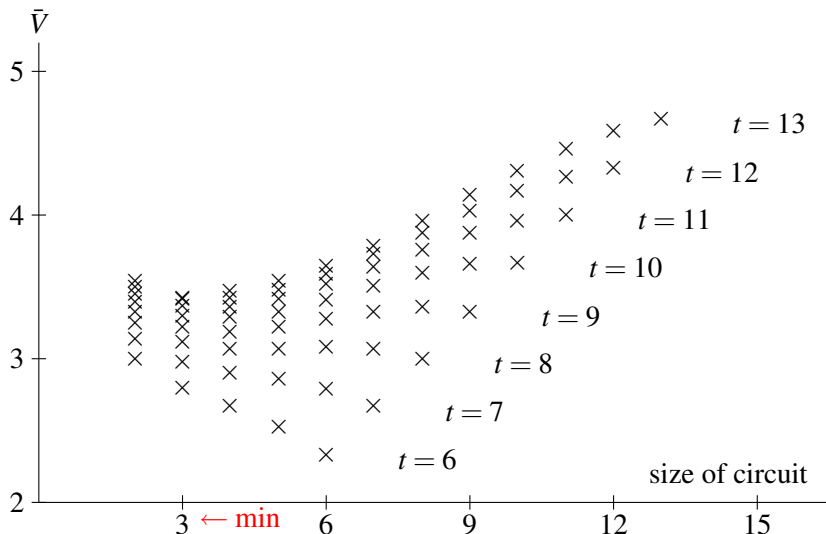
Leaves attached to the same vertex of the circuit

Average pairwise variance is a cubic function of the size of the circuit.

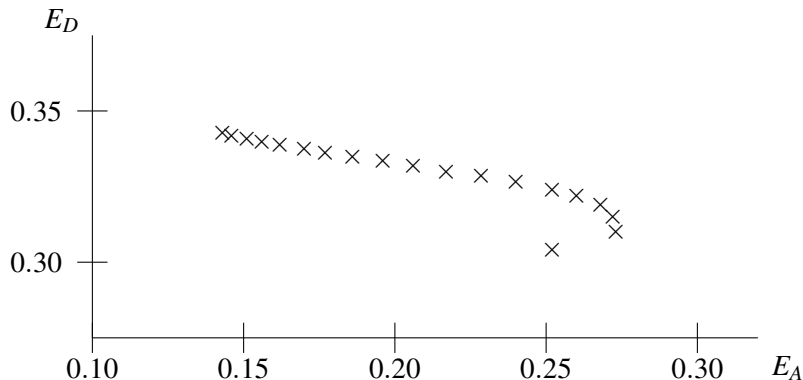


Leaves attached to the same vertex of the circuit

Average pairwise variance is a cubic function of the size of the circuit.



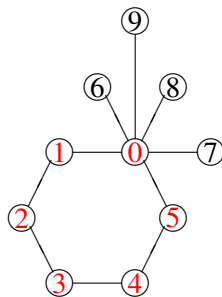
Optimality criteria for designs for 20 treatments in 20 blocks, using the A-optimal design for each size of circuit



The two criteria give essentially reverse rankings.

Assigning colours to a circuit with leaves

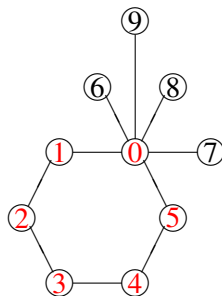
The difference between the colours can be estimated only from the circuit.



Assigning colours to a circuit with leaves

The difference between the colours can be estimated only from the circuit.

More leaves \rightarrow smaller circuit \rightarrow larger variance for colour difference.

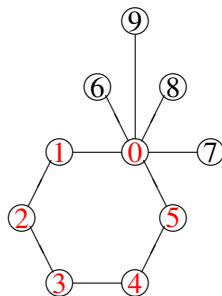


Assigning colours to a circuit with leaves

The difference between the colours can be estimated only from the circuit.

More leaves \rightarrow smaller circuit \rightarrow larger variance for colour difference.

Variance between circuit nodes increases unless the arrows are directed around the circuit.



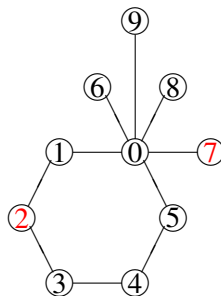
Assigning colours to a circuit with leaves

The difference between the colours can be estimated only from the circuit.

More leaves \rightarrow smaller circuit \rightarrow larger variance for colour difference.

Variance between circuit nodes increases unless the arrows are directed around the circuit.

Variance between a leaf and a circuit node increases because the leaf occurs with only one colour.



Assigning colours to a circuit with leaves

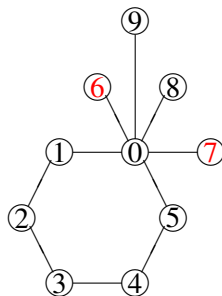
The difference between the colours can be estimated only from the circuit.

More leaves \rightarrow smaller circuit \rightarrow larger variance for colour difference.

Variance between circuit nodes increases unless the arrows are directed around the circuit.

Variance between a leaf and a circuit node increases because the leaf occurs with only one colour.

Variance between leaves increases unless they all have the same colour.



Assigning colours to a circuit with leaves

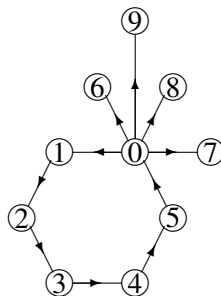
The difference between the colours can be estimated only from the circuit.

More leaves \rightarrow smaller circuit \rightarrow larger variance for colour difference.

Variance between circuit nodes increases unless the arrows are directed around the circuit.

Variance between a leaf and a circuit node increases because the leaf occurs with only one colour.

Variance between leaves increases unless they all have the same colour.



What happens when $b = t + 1$?

A similar analysis shows that the A-optimality and D-optimality criteria conflict when $t \geq 12$.

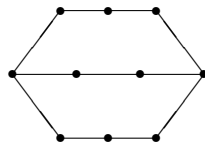
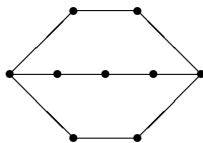
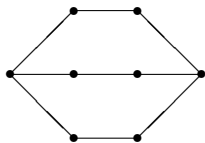
Optimal designs when $b = t + 1$

$t = 8$

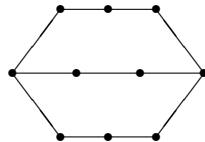
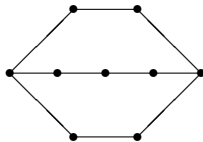
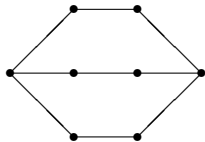
$t = 9$

$t = 10$

D-optimal



A-optimal



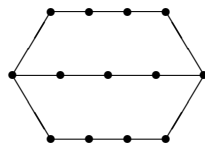
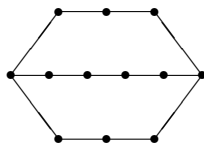
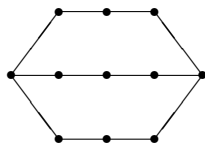
Optimal designs when $b = t + 1$

$t = 11$

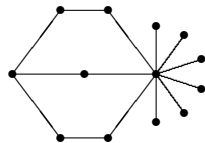
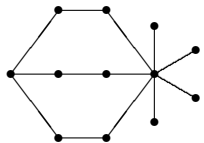
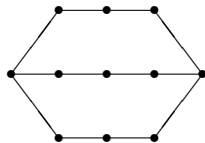
$t = 12$

$t = 13$

D-optimal



A-optimal



What happens for larger values of $b - t$?

Bad news theorem

Given any fixed value of $b - t$, there is a threshold T such that when $t \geq T$ the A- and D-optimality criteria conflict.

When $t \geq T$, the average valency (replication) is much less than 3, so there must be many vertices of valency 2 or many vertices of valency 1 (leaves).

What happens for larger values of $b - t$?

Bad news theorem

Given any fixed value of $b - t$, there is a threshold T such that when $t \geq T$ the A- and D-optimality criteria conflict.

When $t \geq T$, the average valency (replication) is much less than 3, so there must be many vertices of valency 2 or many vertices of valency 1 (leaves).

Many vertices of valency 2 \implies long paths \implies large distances \implies large pairwise variances \implies poor design on A-criterion.

What happens for larger values of $b - t$?

Bad news theorem

Given any fixed value of $b - t$, there is a threshold T such that when $t \geq T$ the A- and D-optimality criteria conflict.

When $t \geq T$, the average valency (replication) is much less than 3, so there must be many vertices of valency 2 or many vertices of valency 1 (leaves).

Many vertices of valency 2 \implies long paths \implies large distances \implies large pairwise variances \implies poor design on A-criterion.

Many leaves \implies few spanning trees \implies poor design on D-criterion.

What happens for larger values of $b - t$?

Bad news theorem

Given any fixed value of $b - t$, there is a threshold T such that when $t \geq T$ the A- and D-optimality criteria conflict.

When $t \geq T$, the average valency (replication) is much less than 3, so there must be many vertices of valency 2 or many vertices of valency 1 (leaves).

Many vertices of valency 2 \implies long paths \implies large distances \implies large pairwise variances \implies poor design on A-criterion.

Many leaves \implies few spanning trees \implies poor design on D-criterion.

A-better designs have many leaves attached to single vertex of some small graph, whereas the D-better designs have no leaves.

How can we construct efficient designs?

Good news theorem

If a given graph has no vertices of valency 1 or 2, then inserting 1 or 2 (or sometimes 3) vertices into the edges of that graph gives a lower average pairwise variance than attaching the extra vertices to a single vertex of that graph.

Strategy for choosing a design when $b \geq 9t/8$

1. Choose the best equireplicate design with replication 3 for $2(b-t)$ treatments in $3(b-t)$ blocks (or with replication 4, for $b-t$ treatments in $2(b-t)$ blocks), **including dye allocation**.
2. Insert up to 2 treatments in each edge.

Strategy for choosing a design when $b \geq 9t/8$

1. Choose the best equireplicate design with replication 3 for $2(b-t)$ treatments in $3(b-t)$ blocks (or with replication 4, for $b-t$ treatments in $2(b-t)$ blocks), including dye allocation.
2. Insert up to 2 treatments in each edge.

Example

Strategy for choosing a design when $b \geq 9t/8$

1. Choose the best equireplicate design with replication 3 for $2(b-t)$ treatments in $3(b-t)$ blocks (or with replication 4, for $b-t$ treatments in $2(b-t)$ blocks), including dye allocation.
2. Insert up to 2 treatments in each edge.

Example

$$t = 12 \Rightarrow b - t = 2$$

\Rightarrow 4 vertices, 6 edges

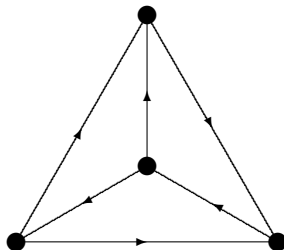
Strategy for choosing a design when $b \geq 9t/8$

1. Choose the best equireplicate design with replication 3 for $2(b-t)$ treatments in $3(b-t)$ blocks (or with replication 4, for $b-t$ treatments in $2(b-t)$ blocks), including dye allocation.
2. Insert up to 2 treatments in each edge.

Example

$$t = 12 \Rightarrow b - t = 2$$

\Rightarrow 4 vertices, 6 edges



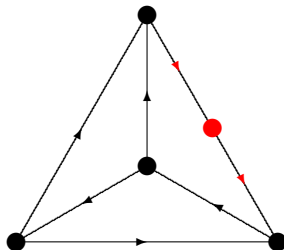
Strategy for choosing a design when $b \geq 9t/8$

1. Choose the best equireplicate design with replication 3 for $2(b-t)$ treatments in $3(b-t)$ blocks (or with replication 4, for $b-t$ treatments in $2(b-t)$ blocks), including dye allocation.
2. Insert up to 2 treatments in each edge.

Example

$$t = 12 \Rightarrow b - t = 2$$

\Rightarrow 4 vertices, 6 edges



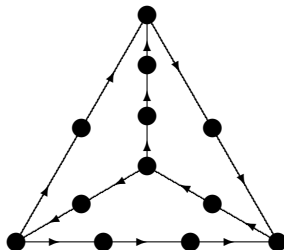
Strategy for choosing a design when $b \geq 9t/8$

1. Choose the best equireplicate design with replication 3 for $2(b-t)$ treatments in $3(b-t)$ blocks (or with replication 4, for $b-t$ treatments in $2(b-t)$ blocks), including dye allocation.
2. Insert up to 2 treatments in each edge.

Example

$$t = 12 \Rightarrow b - t = 2$$

\Rightarrow 4 vertices, 6 edges



Choosing a good equireplicate design with replication 4

1. Ignore the colours.

Choosing a good equireplicate design with replication 4

1. Ignore the colours.
2. Find the best graph with all vertices having valency 4
(smaller problem, can use symmetry to speed up the search).

Choosing a good equireplicate design with replication 4

1. Ignore the colours.
2. Find the best graph with all vertices having valency 4
(smaller problem, can use symmetry to speed up the search).
3. Euler's Theorem (for bridges of Königsberg)
says that the arrows can be put on the edges in such a way that every vertex has two edges coming in and two edges going out.

Choosing a good equireplicate design with replication 3

1. Divide the treatments into two halves: “more red” and “more green”.

Choosing a good equireplicate design with replication 3

1. Divide the treatments into two halves: “more red” and “more green”.
2. Strategy: make every block contain one treatment from each half.

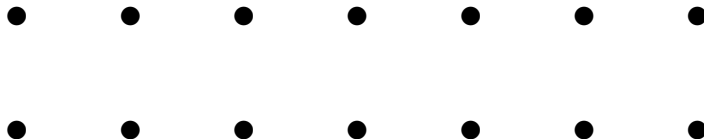
Choosing a good equireplicate design with replication 3

1. Divide the treatments into two halves: “more red” and “more green”.
2. Strategy: make every block contain one treatment from each half.
3. RAB theorem: the best way to do this is to use the Levi graph of the best design for $t/2$ treatments equally replicated in $t/2$ blocks of size 3. (Smaller problem.)

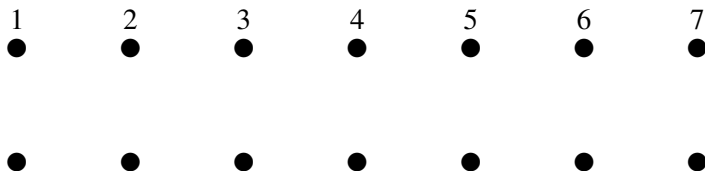
Choosing a good equireplicate design with replication 3

1. Divide the treatments into two halves: “more red” and “more green”.
2. Strategy: make every block contain one treatment from each half.
3. RAB theorem: the best way to do this is to use the Levi graph of the best design for $t/2$ treatments equally replicated in $t/2$ blocks of size 3. (Smaller problem.)
4. Using the algorithm from Hall’s Marriage Theorem, (also König’s Theorem)
orient the edges so that
each lower vertex has 2 out-edges and 1 in-edge and
each upper vertex has 1 out-edge and 2 in-edges.

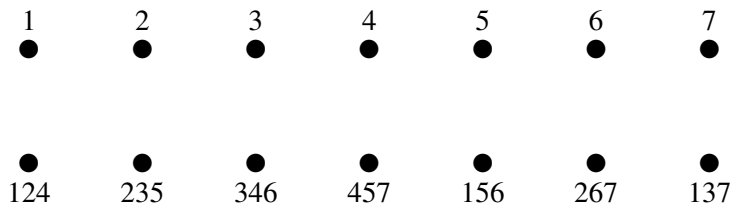
Example for 14 treatments with replication 3



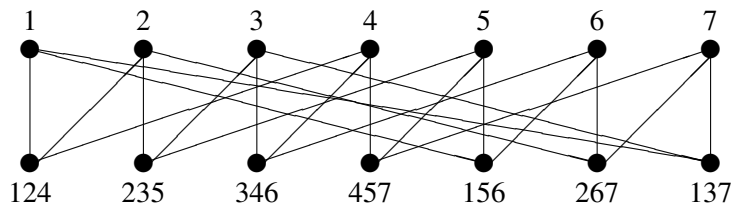
Example for 14 treatments with replication 3



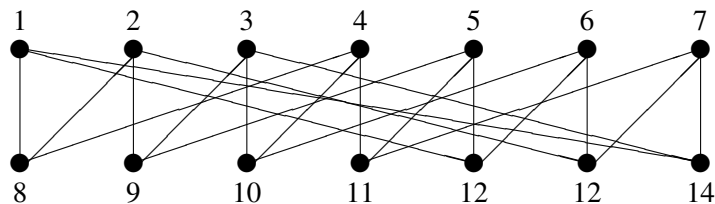
Example for 14 treatments with replication 3



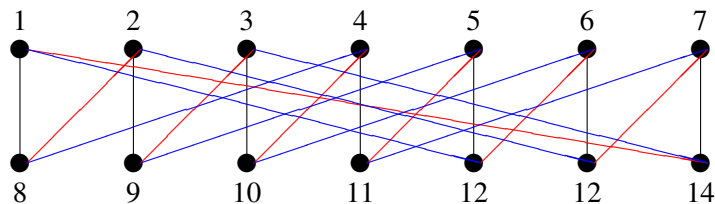
Example for 14 treatments with replication 3



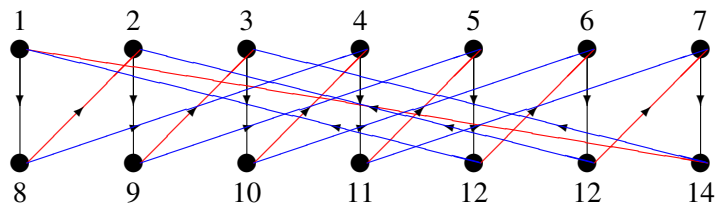
Example for 14 treatments with replication 3



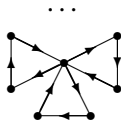
Example for 14 treatments with replication 3



Example for 14 treatments with replication 3



Generic designs with bounded pairwise variance

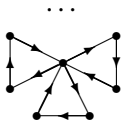


s triangles glued at one vertex

$$t = 2s + 1 \quad b = 3s \quad b/t \approx 1.5$$

$$V_{ij} = 1.33\sigma^2 \text{ (same triangle) or } 2.67\sigma^2 \text{ (otherwise)}$$

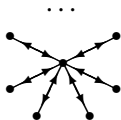
Generic designs with bounded pairwise variance



s triangles glued at one vertex

$$t = 2s + 1 \quad b = 3s \quad b/t \approx 1.5$$

$$V_{ij} = 1.33\sigma^2 \text{ (same triangle) or } 2.67\sigma^2 \text{ (otherwise)}$$

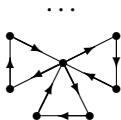


double reference design

$$t = s + 1 \quad b = 2s \quad b/t \approx 2$$

$$V_{ij} = \sigma^2 \text{ (control) or } 2\sigma^2 \text{ (otherwise)}$$

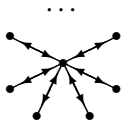
Generic designs with bounded pairwise variance



s triangles glued at one vertex

$$t = 2s + 1 \quad b = 3s \quad b/t \approx 1.5$$

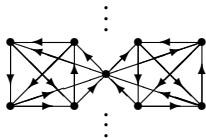
$$V_{ij} = 1.33\sigma^2 \text{ (same triangle) or } 2.67\sigma^2 \text{ (otherwise)}$$



double reference design

$$t = s + 1 \quad b = 2s \quad b/t \approx 2$$

$$V_{ij} = \sigma^2 \text{ (control) or } 2\sigma^2 \text{ (otherwise)}$$

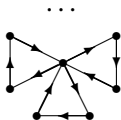


s copies of K_5 glued at one vertex

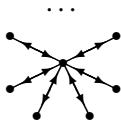
$$t = 4s + 1 \quad b = 10s \quad b/t \approx 2.5$$

$$V_{ij} = 0.8\sigma^2 \text{ (same } K_5) \text{ or } 1.6\sigma^2 \text{ (otherwise)}$$

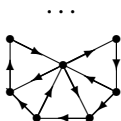
Generic designs with bounded pairwise variance



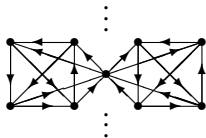
s triangles glued at one vertex
 $t = 2s + 1$ $b = 3s$ $b/t \approx 1.5$
 $V_{ij} = 1.33\sigma^2$ (same triangle) or $2.67\sigma^2$ (otherwise)



double reference design
 $t = s + 1$ $b = 2s$ $b/t \approx 2$
 $V_{ij} = \sigma^2$ (control) or $2\sigma^2$ (otherwise)

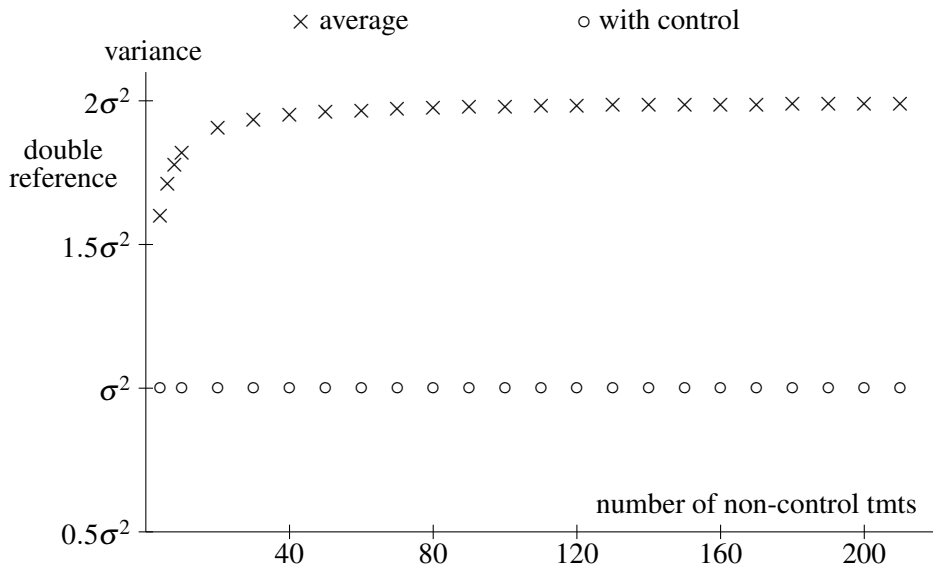


wheel with $2s$ spokes
 $t = 2s + 1$ $b = 4s$ $b/t \approx 2$
 $V_{ij} \leq 0.9\sigma^2$ (control), $\leq 1.8\sigma^2$ (otherwise)

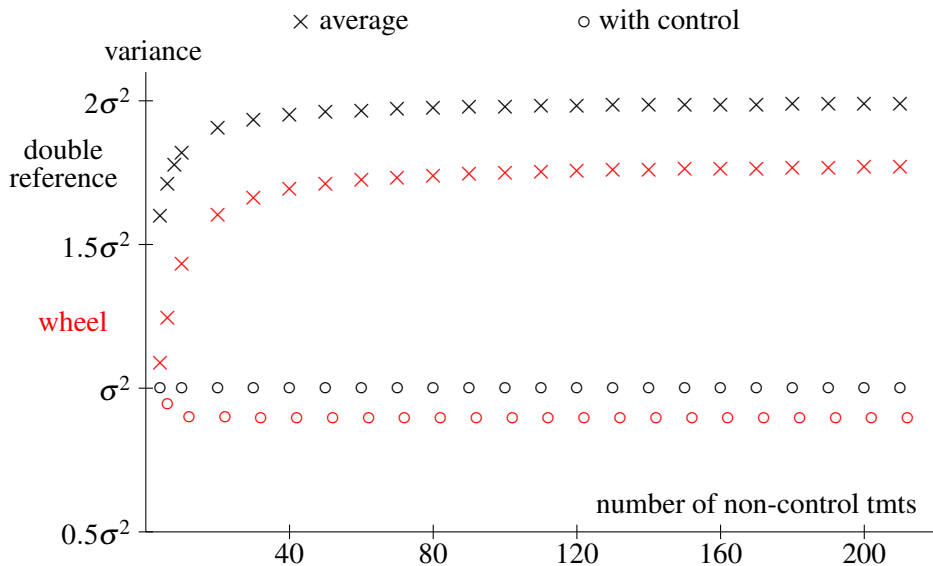


s copies of K_5 glued at one vertex
 $t = 4s + 1$ $b = 10s$ $b/t \approx 2.5$
 $V_{ij} = 0.8\sigma^2$ (same K_5) or $1.6\sigma^2$ (otherwise)

Comparing the wheel design with the double-reference design



Comparing the wheel design with the double-reference design



Proposed strategy

Compare the following.

Proposed strategy

Compare the following.

1. Insert vertices with valency 2 into the best graph with valency 3.

Proposed strategy

Compare the following.

1. Insert vertices with valency 2 into the best graph with valency 3.
2. Insert vertices with valency 2 into the best graph with valency 4.

Proposed strategy

Compare the following.

1. Insert vertices with valency 2 into the best graph with valency 3.
2. Insert vertices with valency 2 into the best graph with valency 4.
3. Glue many leaves to a single vertex of some small graph.

Proposed strategy

Compare the following.

1. Insert vertices with valency 2 into the best graph with valency 3.
2. Insert vertices with valency 2 into the best graph with valency 4.
3. Glue many leaves to a single vertex of some small graph.
4. Glue many triangles to a single vertex of some small graph.

Proposed strategy

Compare the following.

1. Insert vertices with valency 2 into the best graph with valency 3.
2. Insert vertices with valency 2 into the best graph with valency 4.
3. Glue many leaves to a single vertex of some small graph.
4. Glue many triangles to a single vertex of some small graph.
5. Use a wheel design.

Proposed strategy

Compare the following.

1. Insert vertices with valency 2 into the best graph with valency 3.
 - ▶ Needs $1.125 \leq b/t \leq 1.5$.
2. Insert vertices with valency 2 into the best graph with valency 4.
3. Glue many leaves to a single vertex of some small graph.
4. Glue many triangles to a single vertex of some small graph.
5. Use a wheel design.

Proposed strategy

Compare the following.

1. Insert vertices with valency 2 into the best graph with valency 3.
 - ▶ Needs $1.125 \leq b/t \leq 1.5$.
2. Insert vertices with valency 2 into the best graph with valency 4.
 - ▶ Needs $1.2 \leq b/t \leq 2$.
3. Glue many leaves to a single vertex of some small graph.
4. Glue many triangles to a single vertex of some small graph.
5. Use a wheel design.

Proposed strategy

Compare the following.

1. Insert vertices with valency 2 into the best graph with valency 3.
 - ▶ Needs $1.125 \leq b/t \leq 1.5$.
2. Insert vertices with valency 2 into the best graph with valency 4.
 - ▶ Needs $1.2 \leq b/t \leq 2$.
 - ▶ Contrast between dyes does not interfere with comparisons between treatments, but there are more vertices of valency 2.
3. Glue many leaves to a single vertex of some small graph.
4. Glue many triangles to a single vertex of some small graph.
5. Use a wheel design.

Proposed strategy

Compare the following.

1. Insert vertices with valency 2 into the best graph with valency 3.
 - ▶ Needs $1.125 \leq b/t \leq 1.5$.
2. Insert vertices with valency 2 into the best graph with valency 4.
 - ▶ Needs $1.2 \leq b/t \leq 2$.
 - ▶ Contrast between dyes does not interfere with comparisons between treatments, but there are more vertices of valency 2.
 - ▶ In RAB's experience, never beats previous method.
3. Glue many leaves to a single vertex of some small graph.
4. Glue many triangles to a single vertex of some small graph.
5. Use a wheel design.

Proposed strategy

Compare the following.

1. Insert vertices with valency 2 into the best graph with valency 3.
 - ▶ Needs $1.125 \leq b/t \leq 1.5$.
2. Insert vertices with valency 2 into the best graph with valency 4.
 - ▶ Needs $1.2 \leq b/t \leq 2$.
 - ▶ Contrast between dyes does not interfere with comparisons between treatments, but there are more vertices of valency 2.
 - ▶ In RAB's experience, never beats previous method.
3. Glue many leaves to a single vertex of some small graph.
 - ▶ Few spanning trees, but no pairwise variance is bigger than $4\sigma^2$.
4. Glue many triangles to a single vertex of some small graph.
5. Use a wheel design.

Proposed strategy

Compare the following.

1. Insert vertices with valency 2 into the best graph with valency 3.
 - ▶ Needs $1.125 \leq b/t \leq 1.5$.
2. Insert vertices with valency 2 into the best graph with valency 4.
 - ▶ Needs $1.2 \leq b/t \leq 2$.
 - ▶ Contrast between dyes does not interfere with comparisons between treatments, but there are more vertices of valency 2.
 - ▶ In RAB's experience, never beats previous method.
3. Glue many leaves to a single vertex of some small graph.
 - ▶ Few spanning trees, but no pairwise variance is bigger than $4\sigma^2$.
4. Glue many triangles to a single vertex of some small graph.
 - ▶ Needs $b/t \approx 1.5$.
5. Use a wheel design.

Proposed strategy

Compare the following.

1. Insert vertices with valency 2 into the best graph with valency 3.
 - ▶ Needs $1.125 \leq b/t \leq 1.5$.
2. Insert vertices with valency 2 into the best graph with valency 4.
 - ▶ Needs $1.2 \leq b/t \leq 2$.
 - ▶ Contrast between dyes does not interfere with comparisons between treatments, but there are more vertices of valency 2.
 - ▶ In RAB's experience, never beats previous method.
3. Glue many leaves to a single vertex of some small graph.
 - ▶ Few spanning trees, but no pairwise variance is bigger than $4\sigma^2$.
4. Glue many triangles to a single vertex of some small graph.
 - ▶ Needs $b/t \approx 1.5$.
 - ▶ Few spanning trees, but no pairwise variance bigger than $2.67\sigma^2$.
5. Use a wheel design.

Proposed strategy

Compare the following.

1. Insert vertices with valency 2 into the best graph with valency 3.
 - ▶ Needs $1.125 \leq b/t \leq 1.5$.
2. Insert vertices with valency 2 into the best graph with valency 4.
 - ▶ Needs $1.2 \leq b/t \leq 2$.
 - ▶ Contrast between dyes does not interfere with comparisons between treatments, but there are more vertices of valency 2.
 - ▶ In RAB's experience, never beats previous method.
3. Glue many leaves to a single vertex of some small graph.
 - ▶ Few spanning trees, but no pairwise variance is bigger than $4\sigma^2$.
4. Glue many triangles to a single vertex of some small graph.
 - ▶ Needs $b/t \approx 1.5$.
 - ▶ Few spanning trees, but no pairwise variance bigger than $2.67\sigma^2$.
5. Use a wheel design.
 - ▶ Needs $b/t \approx 2$.
 - ▶ No pairwise variance bigger than $1.8\sigma^2$.