

# Polynomial time vertex enumeration of convex polytopes of bounded branch-width

Leen Stougie

In collaboration with Arne Reimers  
Google, Munich

MED2<sup>3</sup>3<sup>2</sup>, London  
July 16, 2018

# Outline

Introduction

Flux-Modules in Metabolic Networks

*k*-Modules

# Vertex enumeration

Given polytope by its outer description

$$P = \{x \in \mathbb{R}^N \mid Sx = b, x \geq 0\}$$

enumerate all its vertices

# Vertex enumeration

Given polytope by its outer description

$$P = \{x \in \mathbb{R}^N \mid Sx = b, x \geq 0\}$$

enumerate all its vertices

Given polytope by its outer description

$$P = \{x \in \mathbb{R}^N \mid Sx = b, x \geq 0\}$$

compute its inner description

$$P = \text{conv.hull}\{x_1, \dots, x_{|V|}\}$$

## Vertex enumeration

Given polytope by its outer description

$$P = \{x \in \mathbb{R}^N \mid Sx = b, x \geq 0\}$$

enumerate all its vertices

Given polytope by its outer description

$$P = \{x \in \mathbb{R}^N \mid Sx = b, x \geq 0\}$$

compute its inner description

$$P = \text{conv.hull}\{x_1, \dots, x_{|V|}\}$$

Can this be done in **total polynomial time**?

## Vertex enumeration

Given polytope by its outer description

$$P = \{x \in \mathbb{R}^N \mid Sx = b, x \geq 0\}$$

enumerate all its vertices

Given polytope by its outer description

$$P = \{x \in \mathbb{R}^N \mid Sx = b, x \geq 0\}$$

compute its inner description

$$P = \text{conv.hull}\{x_1, \dots, x_{|V|}\}$$

Can this be done in **total polynomial time**?

Time polynomial in size of input and output

# Vertex enumeration

**Open Problem:** Can vertex enumeration of a polytope be done in total polynomial time?

# Vertex enumeration

**Open Problem:** Can vertex enumeration of a polytope be done in total polynomial time?

It cannot be done for unbounded polyhedra unless  $P = NP$   
[Boros et al. 97]



# Vertex enumeration

**Open Problem:** Can vertex enumeration of a polytope be done in total polynomial time?

It cannot be done for unbounded polyhedra unless  $P = NP$   
[Boros et al. 97]

It can be done for non-degenerate polytopes [Dyer 83]

# Vertex enumeration

**Open Problem:** Can vertex enumeration of a polytope be done in total polynomial time?

It cannot be done for unbounded polyhedra unless  $P = NP$   
[Boros et al. 97]

It can be done for non-degenerate polytopes [Dyer 83]

Most popular method: Double Description method [Fukuda] or more sophisticated [Terzer & Stelling 08]

# Decomposition of polyhedra

Many graph optimization problems are polytime solvable for graphs with bounded treewidth.

## Decomposition of polyhedra

Many graph optimization problems are polytime solvable for graphs with bounded treewidth.

Tree decomposition and treewidth not applicable to polyhedra.

But the related concepts of [branch-decomposition](#) and [branch-width](#) are!

## Decomposition of polyhedra

Many graph optimization problems are polytime solvable for graphs with bounded treewidth.

Tree decomposition and treewidth not applicable to polyhedra.

But the related concepts of [branch-decomposition](#) and [branch-width](#) are!

Branch-decomposition and branch width defined for [matroids](#)

## Decomposition of polyhedra

Many graph optimization problems are polytime solvable for graphs with bounded treewidth.

Tree decomposition and treewidth not applicable to polyhedra.

But the related concepts of [branch-decomposition](#) and [branch-width](#) are!

Branch-decomposition and branch width defined for [matroids](#)

Our result: For  $P = \{x \in \mathbb{R}^{\mathcal{N}} \mid Sx = b, x \geq 0\}$ , if the branch-width of the [linear matroid on the columns of  \$S\$](#)  is bounded by  $k$ , then we can enumerate all vertices  $\mathcal{V}$  in running time  $O(|\mathcal{N}| |\mathcal{V}|^{O(k)} t)$ , where  $t$  is time for solving some LP's for feasibility checks

# Outline

Introduction

Flux-Modules in Metabolic Networks

*k*-Modules

# Metabolic Network

- ▶ Network of chemical **reactions** together performing some constructive and destructive tasks in a living cell  
e.g. **photosynthesis, glycolysis**



# Metabolic Network

- ▶ Network of chemical **reactions** together performing some constructive and destructive tasks in a living cell  
e.g. **photosynthesis, glycolysis**
- ▶ A reaction transforms some chemical molecules into others
  - **NH<sub>3</sub> and O<sub>2</sub>**

# Metabolic Network

- ▶ Network of chemical **reactions** together performing some constructive and destructive tasks in a living cell  
e.g. **photosynthesis, glycolysis**
- ▶ A reaction transforms some chemical molecules into others
  - **NH<sub>3</sub> and O<sub>2</sub>**

# Metabolic Network

- ▶ Network of chemical **reactions** together performing some constructive and destructive tasks in a living cell  
e.g. **photosynthesis, glycolysis**
- ▶ A reaction transforms some chemical molecules into others  
- **NH<sub>3</sub> and O<sub>2</sub>**
- ▶ Each reaction gives a column of the **stoichiometric matrix**

# Stoichiometric Matrix



	R
.	0
.	0
NH <sub>3</sub>	-1
O <sub>2</sub>	-2
HNO <sub>3</sub>	+1
H <sub>2</sub> O	+1
.	0
.	0

# Flux

- ▶ The **flux**  $v_r$  of a reaction  $r$  is the rate at which the reaction takes place.

# Flux

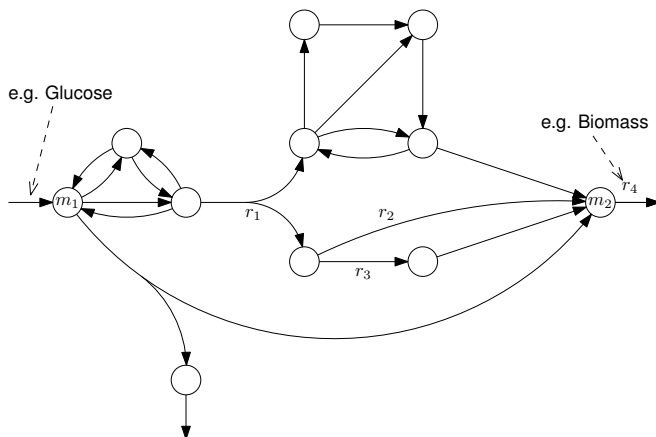
- ▶ The **flux**  $v_r$  of a reaction  $r$  is the rate at which the reaction takes place.
- ▶ The vector  $v$  with for every reaction  $r$  a coordinate  $v_r$  is called the **flux vector**.

# Flux

- ▶ The **flux**  $v_r$  of a reaction  $r$  is the rate at which the reaction takes place.
- ▶ The vector  $v$  with for every reaction  $r$  a coordinate  $v_r$  is called the **flux vector**.
- ▶ **Steady state assumption**

$$Sv = 0, v \geq 0$$

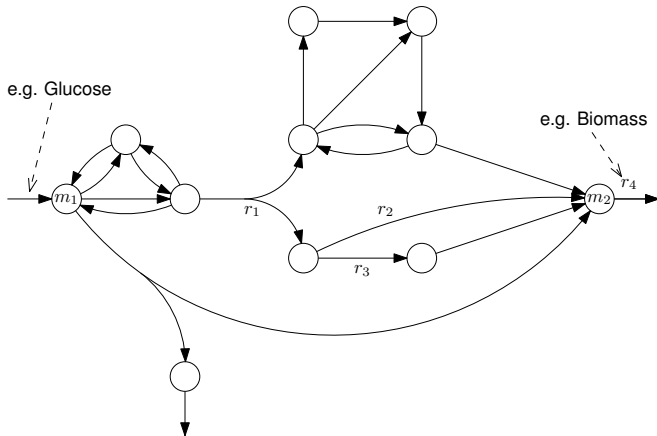
# Running Example



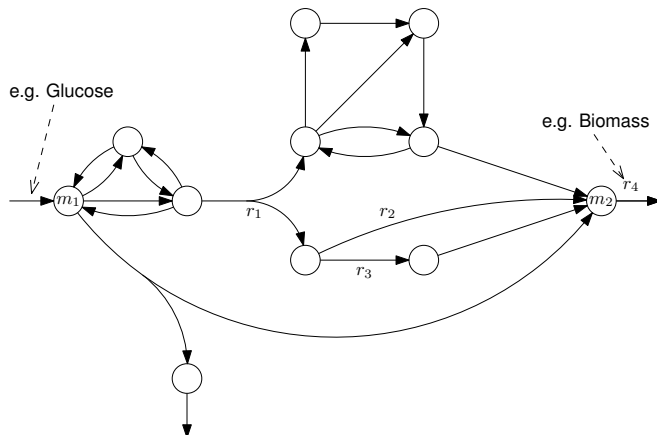
Here all coefficients of the stoichiometric matrix are  $-1, 0, +1$ .



# Running Example

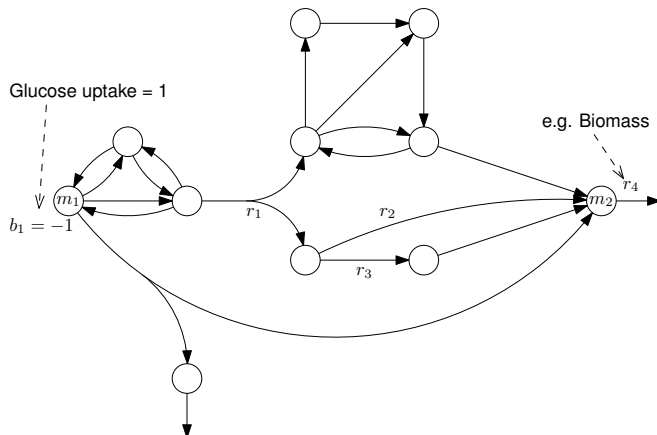


# Running Example



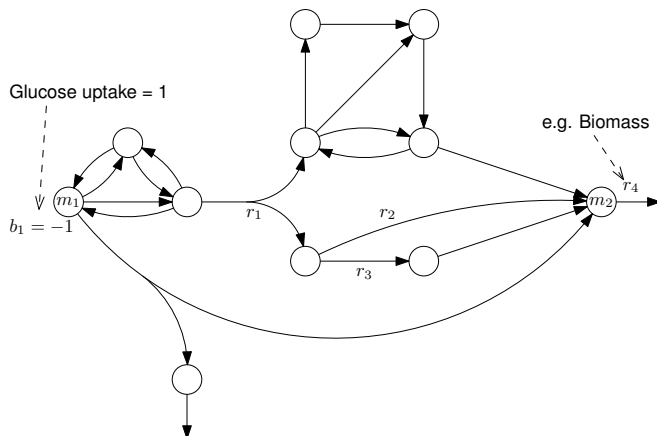
► Flux Space:  $\{v : Sv = 0, v \geq 0\}$

# Running Example



► Flux Space:  $\{v : Sv = b, v \geq 0\}$

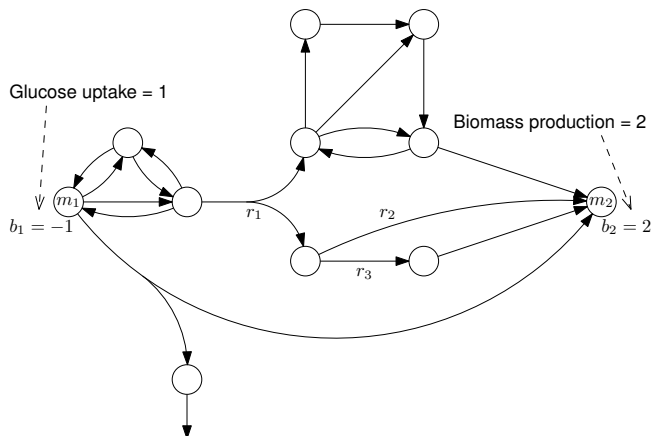
# Running Example



- ▶ Flux Space:  $\{v : Sv = b, v \geq 0\}$
- ▶ Optimize Biomass production (linear programming)

$$\max v_{biomass} \quad \text{subject to } Sv = 0, v_{glucose} = 1$$

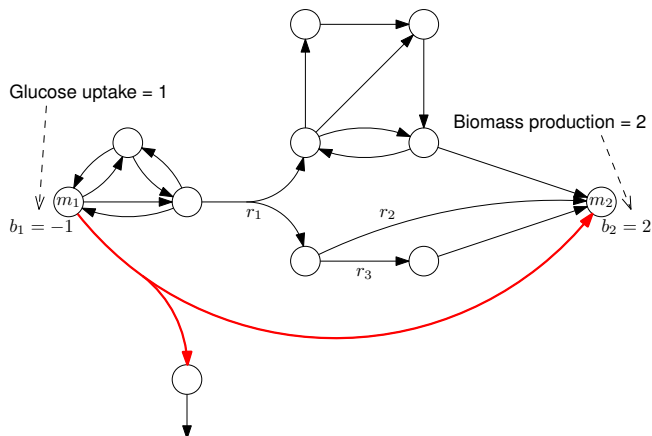
# Running Example



- ▶ Flux Space:  $\{v : Sv = b, v \geq 0\}$
- ▶ Optimize Biomass production (linear programming)

$$\max v_{biomass} \quad \text{subject to } Sv = 0, v_{glucose} = 1$$

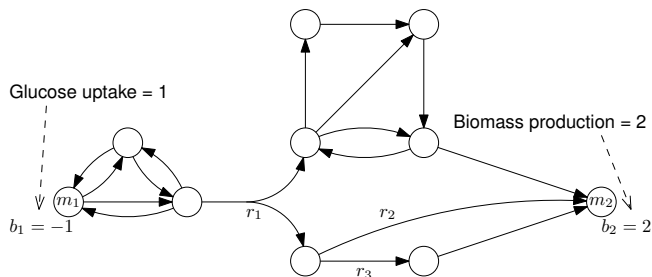
# Running Example



- ▶ Flux Space:  $\{v : Sv = b, v \geq 0\}$
- ▶ Optimize Biomass production (linear programming)

$$\max v_{biomass} \quad \text{subject to } Sv = 0, v_{glucose} = 1$$

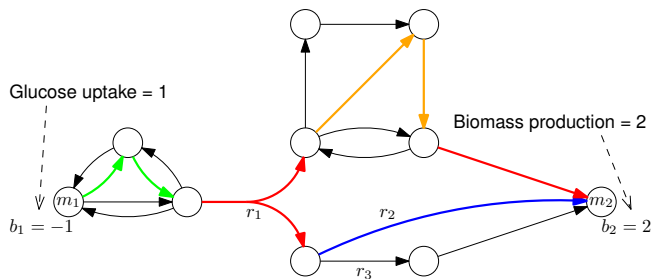
# Running Example



- ▶ Flux Space:  $\{v : Sv = b, v \geq 0\}$
- ▶ Optimize Biomass production (linear programming)

$$\max v_{biomass} \quad \text{subject to } Sv = 0, v_{glucose} = 1$$

# Running Example

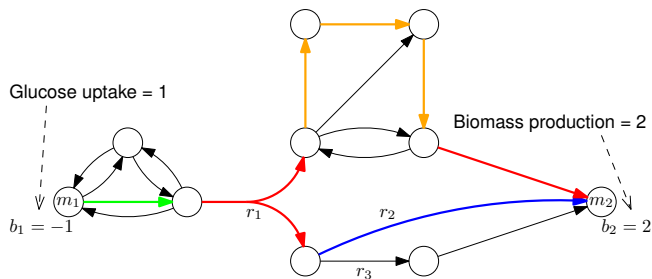


- ▶ Flux Space:  $\{v : Sv = b, v \geq 0\}$
- ▶ Optimize Biomass production (linear programming)

$$\max v_{biomass} \quad \text{subject to } Sv = 0, v_{glucose} = 1$$



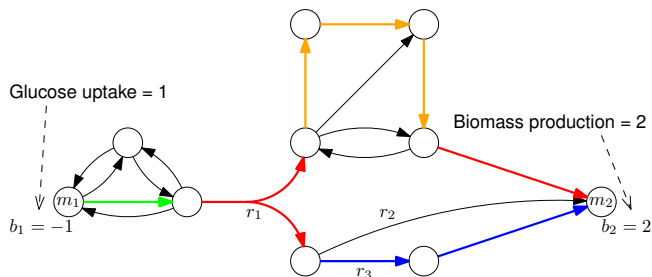
# Running Example



- ▶ Flux Space:  $\{v : Sv = b, v \geq 0\}$
- ▶ Optimize Biomass production (linear programming)

$$\max v_{biomass} \quad \text{subject to } Sv = 0, v_{glucose} = 1$$

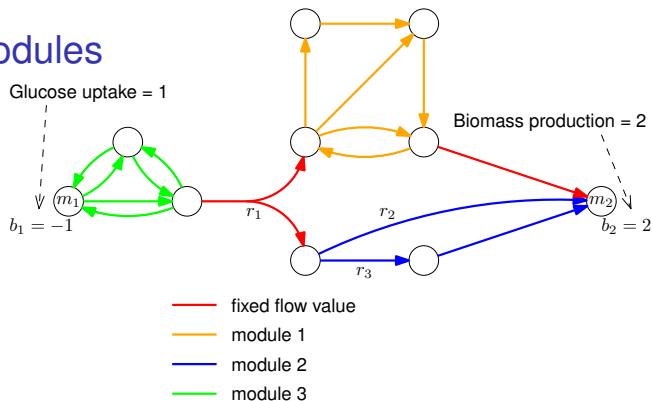
# Running Example



- ▶ Flux Space:  $\{v : Sv = b, v \geq 0\}$
- ▶ Optimize Biomass production (linear programming)

$$\max v_{biomass} \quad \text{subject to } Sv = 0, v_{glucose} = 1$$

# Flux-Modules



## Observation (Kelk, Olivier, S., Bruggeman '12)

Reaction rates in the **green module** are **independent** from reaction rates in the **orange module** are **independent** from reaction rates in the **blue module**.

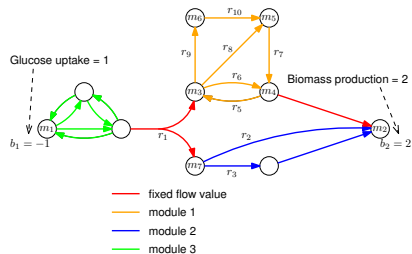
Kelk et al., Optimal flux spaces of genome-scale stoichiometric models are determined by a few subnetworks  
*Nature Scientific Reports*, 2:580, 2012.

# Flux-Modules: A Definition

## Notation:

- ▶  $\mathcal{N}$  reactions  
(variables, columns)
- ▶  $\mathcal{M}$  metabolites  
(constraints, rows)
- ▶  $S$  stoichiometric matrix
- ▶  $P \subseteq \mathbb{R}^{\mathcal{N}}$  flux space: In Ex.

$$\{v : Sv = 0, v_{\text{glucose}} = 1, v_{\text{biomass}} = 2, v \geq 0\}$$



## Definition (Reimers '13)

$A \subseteq \mathcal{N}$  is a **P-module** if  $\exists d \in \mathbb{R}^{\mathcal{M}}$  s.t.  $S_A v_A = d$  for all  $v \in P$ .

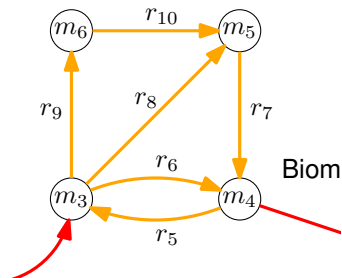
- ▶ A module is a set of reactions  $A$ .
- ▶ The **interface flux**  $d = S_A v_A$  of a module is constant for all feasible flux vectors ( $v \in P$ ).

# Flux-Modules: A Definition

## Notation:

- ▶  $\mathcal{N}$  reactions  
(variables, columns)
- ▶  $\mathcal{M}$  metabolites  
(constraints, rows)
- ▶  $S$  stoichiometric matrix
- ▶  $P \subseteq \mathbb{R}^{\mathcal{N}}$  flux space: In Ex.

$$\{v : Sv = 0, v_{\text{glucose}} = 1, v_{\text{biomass}} = 2, v \geq 0\}$$



$$d_3 = -1, d_4 = 1, \\ d_i = 0 \forall i \neq 3, 4$$

## Definition (Reimers '13)

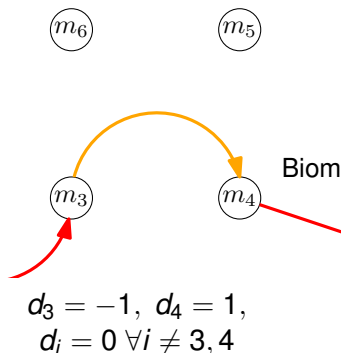
$A \subseteq \mathcal{N}$  is a **P-module** if  $\exists d \in \mathbb{R}^{\mathcal{M}}$  s.t.  $S_A v_A = d$  for all  $v \in P$ .

- ▶ A module is a set of reactions  $A$ .
- ▶ The **interface flux**  $d = S_A v_A$  of a module is constant for all feasible flux vectors ( $v \in P$ ).

# Flux-Modules: A Definition

## Notation:

- ▶  $\mathcal{N}$  reactions  
(variables, columns)
- ▶  $\mathcal{M}$  metabolites  
(constraints, rows)
- ▶  $S$  stoichiometric matrix
- ▶  $P \subseteq \mathbb{R}^{\mathcal{N}}$  flux space: In Ex.  
 $\{v : Sv = 0, v_{glucose} = 1, v_{biomass} = 2, v \geq 0\}$



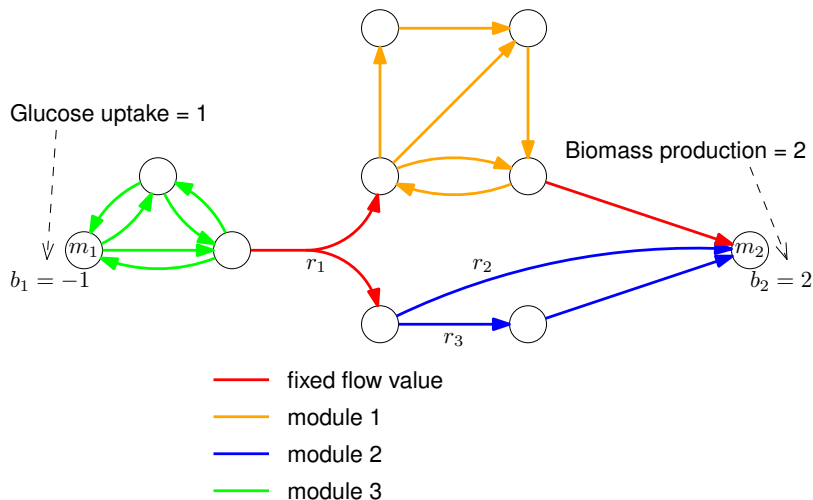
## Definition (Reimers '13)

$A \subseteq \mathcal{N}$  is a **P-module** if  $\exists d \in \mathbb{R}^{\mathcal{M}}$  s.t.  $S_A v_A = d$  for all  $v \in P$ .

- ▶ A module is a set of reactions  $A$ .
- ▶ The **interface flux**  $d = S_A v_A$  of a module is constant for all feasible flux vectors ( $v \in P$ ).

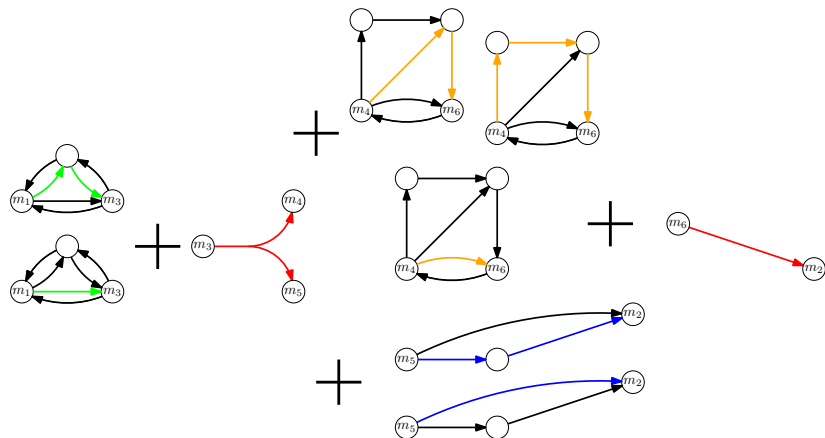
# Decomposition of Elementary Flux Modes (EFM)

A graphical visualization of all 12 EFMs in the example network



# Decomposition of Elementary Flux Modes (EFM)

A graphical visualization of all 12 EFMs in the example network





# Outline

Introduction

Flux-Modules in Metabolic Networks

*k*-Modules

# k-modules

## Definition (module)

$A \subseteq \mathcal{N}$  is a module of  $P$  if there exists a  $d \in \mathbb{R}^M$ , s.t. for all  $x \in P$

$$S_A x_A = d \quad .$$

# k-modules

## Definition (*k*-module)

$A \subseteq \mathcal{N}$  is a *k*-module of  $P$  if there exists a  $d \in \mathbb{R}^{\mathcal{M}}$ ,  $D \in \mathbb{R}^{\mathcal{M} \times k}$   
s.t. for all  $x \in P$  exists a  $\alpha \in \mathbb{R}^k$  with

$$S_{AXA} = d + D\alpha.$$

# k-modules

## Definition (k-module)

$A \subseteq \mathcal{N}$  is a **k-module** of  $P$  if there exists a  $d \in \mathbb{R}^M$ ,  $D \in \mathbb{R}^{M \times k}$   
s.t. for all  $x \in P$  **exists a  $\alpha \in \mathbb{R}^k$  with**

$$S_{AXA} = d + D\alpha.$$

For  $P \subset \{x \in \mathbb{R}^N \mid Sx = b\}$  we have

# k-modules

## Definition (k-module)

$A \subseteq \mathcal{N}$  is a **k-module** of  $P$  if there exists a  $d \in \mathbb{R}^M$ ,  $D \in \mathbb{R}^{M \times k}$   
s.t. for all  $x \in P$  **exists a  $\alpha \in \mathbb{R}^k$  with**

$$S_{AXA} = d + D\alpha.$$

For  $P \subset \{x \in \mathbb{R}^{\mathcal{N}} \mid Sx = b\}$  we have

- 1) Flux module is a 0-module

# k-modules

## Definition (*k*-module)

$A \subseteq \mathcal{N}$  is a *k*-module of  $P$  if there exists a  $d \in \mathbb{R}^M$ ,  $D \in \mathbb{R}^{M \times k}$   
s.t. for all  $x \in P$  exists a  $\alpha \in \mathbb{R}^k$  with

$$S_{AXA} = d + D\alpha.$$

For  $P \subset \{x \in \mathbb{R}^N \mid Sx = b\}$  we have

- 1) Flux module is a 0-module
- 2) Every set with  $k$  elements is a *k*-module

# k-modules

## Definition (*k*-module)

$A \subseteq \mathcal{N}$  is a *k*-module of  $P$  if there exists a  $d \in \mathbb{R}^M$ ,  $D \in \mathbb{R}^{M \times k}$   
s.t. for all  $x \in P$  exists a  $\alpha \in \mathbb{R}^k$  with

$$S_{AX}A = d + D\alpha.$$

For  $P \subset \{x \in \mathbb{R}^{\mathcal{N}} \mid Sx = b\}$  we have

- 1) Flux module is a 0-module
- 2) Every set with  $k$  elements is a  $k$ -module
- 3)  $A$  is a  $k - 1$ -module  $\Rightarrow A$  is a  $k$ -module

# k-modules

## Definition (k-module)

$A \subseteq \mathcal{N}$  is a  $k$ -module of  $P$  if there exists a  $d \in \mathbb{R}^{\mathcal{M}}$ ,  $D \in \mathbb{R}^{\mathcal{M} \times k}$  s.t. for all  $x \in P$  exists a  $\alpha \in \mathbb{R}^k$  with

$$S_{AXA} = d + D\alpha.$$

For  $P \subset \{x \in \mathbb{R}^{\mathcal{N}} \mid Sx = b\}$  we have

- 1) Flux module is a 0-module
- 2) Every set with  $k$  elements is a  $k$ -module
- 3)  $A$  is a  $k - 1$ -module  $\Rightarrow A$  is a  $k$ -module
- 5)  $A$  is a  $k$ -module if and only if  $\mathcal{N} \setminus A$  is a  $k$ -module



# k-modules

## Definition (k-module)

$A \subseteq \mathcal{N}$  is a  $k$ -module of  $P$  if there exists a  $d \in \mathbb{R}^M$ ,  $D \in \mathbb{R}^{M \times k}$  s.t. for all  $x \in P$  exists a  $\alpha \in \mathbb{R}^k$  with

$$S_A x_A = d + D\alpha.$$

For  $P \subset \{x \in \mathbb{R}^{\mathcal{N}} \mid Sx = b\}$  we have

- 1) Flux module is a 0-module
- 2) Every set with  $k$  elements is a  $k$ -module
- 3)  $A$  is a  $k - 1$ -module  $\Rightarrow A$  is a  $k$ -module
- 5)  $A$  is a  $k$ -module if and only if  $\mathcal{N} \setminus A$  is a  $k$ -module
- 6)  $\emptyset$  is a  $k$ -module for all  $k$

# k-modules

## Definition (*k*-module)

$A \subseteq \mathcal{N}$  is a *k*-module of  $P$  if there exists a  $d \in \mathbb{R}^M$ ,  $D \in \mathbb{R}^{M \times k}$   
s.t. for all  $v \in P$  exists a  $\alpha \in \mathbb{R}^k$  with

$$S_A v_A = d + D\alpha.$$

If  $d = 0$  we call  $A$  a **linear** *k*-module

# k-modules

## Definition (*k*-module)

$A \subseteq \mathcal{N}$  is a *k*-module of  $P$  if there exists a  $d \in \mathbb{R}^M$ ,  $D \in \mathbb{R}^{M \times k}$   
s.t. for all  $v \in P$  exists a  $\alpha \in \mathbb{R}^k$  with

$$S_A v_A = d + D\alpha.$$

Notice that  $D$  is not unique but  $\langle D \rangle$ , the **span** of  $D$  is unique.

# k-modules

## Definition (*k*-module)

$A \subseteq \mathcal{N}$  is a *k*-module of  $P$  if there exists a  $d \in \mathbb{R}^M$ ,  $D \in \mathbb{R}^{M \times k}$   
s.t. for all  $v \in P$  exists a  $\alpha \in \mathbb{R}^k$  with

$$S_A v_A = d + D\alpha.$$

Notice that  $D$  is not unique but  $\langle D \rangle$ , the **span** of  $D$  is unique.

**Allow decomposition of general polyhedra**

# k-modules

## Definition (*k*-module)

$A \subseteq \mathcal{N}$  is a *k*-module of  $P$  if there exists a  $d \in \mathbb{R}^M$ ,  $D \in \mathbb{R}^{M \times k}$   
s.t. for all  $v \in P$  exists a  $\alpha \in \mathbb{R}^k$  with

$$S_A v_A = d + D\alpha.$$

Notice that  $D$  is not unique but  $\langle D \rangle$ , the **span** of  $D$  is unique.

### **Allow decomposition of general polyhedra**

- ▶ *k*-modules relate to *k*-separations of the matroid with ground set the columns of the constraint matrix

# *k*-modules on linear vector spaces

$$P \subset \{x \in \mathbb{R}^N \mid Sx = b\}$$

# k-modules on linear vector spaces

$$P \subset \{x \in \mathbb{R}^{\mathcal{N}} \mid Sx = b\}$$

Let  $\ker(S) = \{x \in \mathbb{R}^{\mathcal{N}} \mid Sx = 0\}$ , the kernel of  $S$

## Theorem

*A is a k-module for P  $\Leftrightarrow$  A is a k-module for ker(S)*

# k-modules on linear vector spaces

$$P \subset \{x \in \mathbb{R}^N \mid Sx = b\}$$

Let  $\ker(S) = \{x \in \mathbb{R}^N \mid Sx = 0\}$ , the kernel of  $S$

## Theorem

*A is a k-module for P  $\Leftrightarrow$  A is a k-module for  $\ker(S)$*

Under the condition that no  $x_i$  has fixed value on  $P$   
which can be ensured by preprocessing if necessary.



# *k*-modules and Matroids

## Definition (*k*-separator, Oxley 2011)

Let  $M$  be a matroid on the element set  $\mathcal{N}$ . A set  $A \subseteq \mathcal{N}$  is a  $k$ -separator if and only if

$$\text{rank}(A) + \text{rank}(\mathcal{N} \setminus A) - \text{rank}(\mathcal{N}) < k.$$

# *k*-modules and Matroids

## Definition (*k*-separator, Oxley 2011)

Let  $M$  be a matroid on the element set  $\mathcal{N}$ . A set  $A \subseteq \mathcal{N}$  is a  $k$ -separator if and only if

$$\text{rank}(A) + \text{rank}(\mathcal{N} \setminus A) - \text{rank}(\mathcal{N}) < k.$$

Separation is a measure of connectivity of the matroid

# *k*-modules and Matroids

## Definition (*k*-separator, Oxley 2011)

Let  $M$  be a matroid on the element set  $\mathcal{N}$ . A set  $A \subseteq \mathcal{N}$  is a  $k$ -separator if and only if

$$\text{rank}(A) + \text{rank}(\mathcal{N} \setminus A) - \text{rank}(\mathcal{N}) < k.$$

# k-modules and Matroids

## Definition (*k*-separator, Oxley 2011)

Let  $M$  be a matroid on the element set  $\mathcal{N}$ . A set  $A \subseteq \mathcal{N}$  is a  $k$ -separator if and only if

$$\text{rank}(A) + \text{rank}(\mathcal{N} \setminus A) - \text{rank}(\mathcal{N}) < k.$$

## Theorem

$A \subseteq \mathcal{N}$  is a  $(\ker S)$ - $k$ -module if and only if  $A$  is a  $k + 1$ -separator in the linear matroid  $M$  represented by  $S$ .

# Branch Decomposition of columns of $S$

## Definition (branch-width)

- ▶ A *branch decomposition*  $(T, \tau)$  consists of a tree  $T$  with nodes of degree 3 and 1 and a bijective map  $\tau : T \rightarrow \mathcal{N}$ . Define  $\tau(A) := \{\tau(a) : a \in A\}$ .
- ▶ The *width* of edge  $e$  of  $T$  is  $\rho(\tau(A_e))$ , where  $(A_e, B_e)$  the partition of the leaves of  $T$  given by  $T \setminus e$ . (Note that  $\rho(A) = \rho(\mathcal{N} \setminus A)$ .)
- ▶ The width of a branch decomposition is the maximal width of an edge  $e \in T$ .
- ▶ The *branch-width* of  $M$  is the minimal width of all possible branch-decompositions.

With connectivity function

$$\rho(A) := \text{rank}(A) + \text{rank}(\mathcal{N} \setminus A) - \text{rank}(\mathcal{N}) + 1$$

# Branch Decomposition of columns of $S$

## Definition (branch-width)

- ▶ A *branch decomposition*  $(T, \tau)$  consists of a tree  $T$  with nodes of degree 3 and 1 and a bijective map  $\tau : T \rightarrow \mathcal{N}$ . Define  $\tau(A) := \{\tau(a) : a \in A\}$ .
- ▶ The *width* of edge  $e$  of  $T$  is  $\rho(\tau(A_e))$ , where  $(A_e, B_e)$  the partition of the leaves of  $T$  given by  $T \setminus e$ . (Note that  $\rho(A) = \rho(\mathcal{N} \setminus A)$ .)
- ▶ The width of a branch decomposition is the maximal width of an edge  $e \in T$ .
- ▶ The *branch-width* of  $M$  is the minimal width of all possible branch-decompositions.

With connectivity function

$$\rho(A) := \text{rank}(A) + \text{rank}(\mathcal{N} \setminus A) - \text{rank}(\mathcal{N}) + 1$$

**Note:**  $\rho(A) \leq k + 1 \Leftrightarrow A$  is  $k + 1$ -separator  $\Leftrightarrow A$  is  $k$ -module for  $P$

# Rooted Decomposition

Suppose a branch decomposition of  $\mathcal{N}$  of width  $k + 1$ ;  
Create a hierarchical family  $\text{Mod}$  of  $k$ -modules

# Rooted Decomposition

Suppose a branch decomposition of  $\mathcal{N}$  of width  $k + 1$ ;  
Create a hierarchical family  $\text{Mod}$  of  $k$ -modules

- ▶ Take an arbitrary edge of the branch decomposition,



# Rooted Decomposition

Suppose a branch decomposition of  $\mathcal{N}$  of width  $k + 1$ ;  
Create a hierarchical family  $\text{Mod}$  of  $k$ -modules

- ▶ Take an arbitrary edge of the branch decomposition,
- ▶ subdivide it and make the created vertex the root corresponding to  $\mathcal{N}$ ,

# Rooted Decomposition

Suppose a branch decomposition of  $\mathcal{N}$  of width  $k + 1$ ;  
Create a hierarchical family  $\text{Mod}$  of  $k$ -modules

- ▶ Take an arbitrary edge of the branch decomposition,
- ▶ subdivide it and make the created vertex the root corresponding to  $\mathcal{N}$ ,
- ▶ Direct all other edges away from the root.

# Rooted Decomposition

Suppose a branch decomposition of  $\mathcal{N}$  of width  $k + 1$ ;  
Create a hierarchical family  $\text{Mod}$  of  $k$ -modules

- ▶ Take an arbitrary edge of the branch decomposition,
- ▶ subdivide it and make the created vertex the root corresponding to  $\mathcal{N}$ ,
- ▶ Direct all other edges away from the root.

Every internal node of this rooted binary tree corresponds to the set of elements in  $\text{Mod}$  formed by the leaves in the subtree below it.

## Rooted Decomposition

Suppose a branch decomposition of  $\mathcal{N}$  of width  $k + 1$ ;  
Create a hierarchical family  $\text{Mod}$  of  $k$ -modules

- ▶ Take an arbitrary edge of the branch decomposition,
- ▶ subdivide it and make the created vertex the root corresponding to  $\mathcal{N}$ ,
- ▶ Direct all other edges away from the root.

Every internal node of this rooted binary tree corresponds to the set of elements in  $\text{Mod}$  formed by the leaves in the subtree below it.

The hierarchic family  $\text{Mod}$  of subsets of  $\mathcal{N}$  thus created has property: If  $C \in \text{Mod}$  then  $\exists A, B \in \text{Mod}, A \cap B = \emptyset, C = A \cup B$ .

## Vertex enumeration

For module  $A \in \text{Mod}$  let

$$P^A := \{x \in \mathbb{R}^A : S_A x = D^A \alpha + d, x \geq 0, \exists \alpha \in \mathbb{R}^k\}.$$

## Vertex enumeration

For module  $A \in \text{Mod}$  let

$$P^A := \{x \in \mathbb{R}^A : S_A x = D^A \alpha + d, x \geq 0, \exists \alpha \in \mathbb{R}^k\}.$$

Idea: For  $C = A \cup B$  combine vertices of  $P^A$  with vertices of  $P^B$  into vertices of  $P^C$ .

## Vertex enumeration

For module  $A \in \text{Mod}$  let

$$P^A := \{x \in \mathbb{R}^A : S_A x = D^A \alpha + d, x \geq 0, \exists \alpha \in \mathbb{R}^k\}.$$

Idea: For  $C = A \cup B$  combine vertices of  $P^A$  with vertices of  $P^B$  into vertices of  $P^C$ .

Cartesian product only works if  $A$  and  $B$  are 0-modules (1-separators)! (restricted to  $C$ )

## Vertex enumeration

For module  $A \in \text{Mod}$  let

$$P^A := \{x \in \mathbb{R}^A : S_A x = D^A \alpha + d, x \geq 0, \exists \alpha \in \mathbb{R}^k\}.$$

Idea: For  $C = A \cup B$  combine vertices of  $P^A$  with vertices of  $P^B$  into vertices of  $P^C$ .

Cartesian product only works if  $A$  and  $B$  are 0-modules (1-separators)! (restricted to  $C$ )

Every face of  $P$  is determined uniquely by  $Sx = b$  and a subset of the non-negativity restrictions being tight: for some  $F \in \mathcal{N}$   
 $x_F = 0$



## Vertex enumeration

For module  $A \in \text{Mod}$  let

$$P^A := \{x \in \mathbb{R}^A : S_A x = D^A \alpha + d, x \geq 0, \exists \alpha \in \mathbb{R}^k\}.$$

Idea: For  $C = A \cup B$  combine vertices of  $P^A$  with vertices of  $P^B$  into vertices of  $P^C$ .

Cartesian product only works if  $A$  and  $B$  are 0-modules (1-separators)! (restricted to  $C$ )

Every face of  $P$  is determined uniquely by  $Sx = b$  and a subset of the non-negativity restrictions being tight: for some  $F \in \mathcal{N}$   $x_F = 0$  a **face** of  $P$

## Vertex enumeration

For module  $A \in \text{Mod}$  let

$$P^A := \{x \in \mathbb{R}^A : S_A x = D^A \alpha + d, x \geq 0, \exists \alpha \in \mathbb{R}^k\}.$$

Idea: For  $C = A \cup B$  combine vertices of  $P^A$  with vertices of  $P^B$  into vertices of  $P^C$ .

Cartesian product only works if  $A$  and  $B$  are 0-modules (1-separators)! (restricted to  $C$ )

Every face of  $P$  is determined uniquely by  $Sx = b$  and a subset of the non-negativity restrictions being tight: for some  $F \in \mathcal{N}$   $x_F = 0$  a **face** of  $P$

**Definition (A-face (combinatorial represent. of A-face))**

For  $A \subseteq \mathcal{N}$  a set  $F \subseteq A$  is called a *A-face* if there exists a  $x \in P$  with  $x_F = 0$  and  $x_{A \setminus F} > 0$ .

# Vertex enumeration

## Definition ( $A$ -cface)

For  $A \subseteq \mathcal{N}$  a set  $F \subseteq A$  is called a  $A$ -cface if there exists a  $x \in P$  with  $x_F = 0$  and  $x_{A \setminus F} > 0$ .

In fact we are interested in enumerating

## Definition (vertex inducing $A$ -cface)

For  $A \subseteq \mathcal{N}$  a set  $F \subseteq A$  is called *vertex inducing  $A$ -cface* if there exists a vertex  $v$  of  $P$  with  $v_F = 0$  and  $v_{A \setminus F} > 0$ .

# Vertex enumeration

## Definition ( $A$ -cface)

For  $A \subseteq \mathcal{N}$  a set  $F \subseteq A$  is called a  $A$ -cface if there exists a  $x \in P$  with  $x_F = 0$  and  $x_{A \setminus F} > 0$ .

In fact we are interested in enumerating

## Definition (vertex inducing $A$ -cface)

For  $A \subseteq \mathcal{N}$  a set  $F \subseteq A$  is called *vertex inducing  $A$ -cface* if there exists a vertex  $v$  of  $P$  with  $v_F = 0$  and  $v_{A \setminus F} > 0$ .

Testing if  $F \subset A$  is vertex-inducing is NP-hard [Fukuda EA 97]

## Vertex enumeration

### Definition ( $A$ -cface)

For  $A \subseteq \mathcal{N}$  a set  $F \subseteq A$  is called a  $A$ -cface if there exists a  $x \in P$  with  $x_F = 0$  and  $x_{A \setminus F} > 0$ .

In fact we are interested in enumerating

### Definition (vertex inducing $A$ -cface)

For  $A \subseteq \mathcal{N}$  a set  $F \subseteq A$  is called *vertex inducing  $A$ -cface* if there exists a vertex  $v$  of  $P$  with  $v_F = 0$  and  $v_{A \setminus F} > 0$ .

Testing if  $F \subset A$  is vertex-inducing is NP-hard [Fukuda EA 97]

### Definition (injective $A$ -cface)

For  $A \subseteq \mathcal{N}$  set  $F \subseteq A$  is injective  $A$ -cface if  $\nexists y, z \in P^A : y_F = z_F = 0$  with  $S_{Ay} = S_{Az}$ ; i.e.  $S_A$  injective on  $\{x \in P^A : x_F = 0\}$ .

## Vertex enumeration

### Definition (*A*-cface)

For  $A \subseteq \mathcal{N}$  a set  $F \subseteq A$  is called a *A-cface* if there exists a  $x \in P$  with  $x_F = 0$  and  $x_{A \setminus F} > 0$ .

In fact we are interested in enumerating

### Definition (vertex inducing *A*-cface)

For  $A \subseteq \mathcal{N}$  a set  $F \subseteq A$  is called *vertex inducing A-cface* if there exists a vertex  $v$  of  $P$  with  $v_F = 0$  and  $v_{A \setminus F} > 0$ .

Testing if  $F \subset A$  is vertex-inducing is NP-hard [Fukuda EA 97]

### Definition (injective *A*-cface)

For  $A \subseteq \mathcal{N}$  set  $F \subseteq A$  is injective *A-cface* if  $\nexists y, z \in P^A : y_F = z_F = 0$  with  $S_{Ay} = S_{Az}$ ; i.e.  $S_A$  injective on  $\{x \in P^A : x_F = 0\}$ .

Testing if  $F \subset A$  is injective can be done in polytime

# Injective cFace Enumeration

Recursively for every  $C = A \dot{\cup} B$ .

Let  $\mathcal{F}^A :=$  Injective  $A$ -cFaces

Let  $\mathcal{F}^B :=$  Injective  $B$ -cFaces

Construct

$$\mathcal{F} := \{F^A \cup F^B : F^A \in \mathcal{F}^A, F^B \in \mathcal{F}^B\}$$

For every  $F \in \mathcal{F}$  test if it is a cface and injective for  $C$ .

If not delete  $F$  from  $\mathcal{F}$

Set the resulting set  $\mathcal{F}$  to  $\mathcal{F}^C$

## Vertex enumeration

We have enumerated all injective  $\mathcal{N}$ -cfaces, whereas we should have enumerated all vertex-induced  $\mathcal{N}$ -cfaces :-)



# Vertex enumeration

We have enumerated all injective  $\mathcal{N}$ -cfaces, whereas we should have enumerated all vertex-induced  $\mathcal{N}$ -cfaces :-)

## Theorem

*Let  $A \in \text{Mod}$  be a 0-module. Then, a  $A$ -cface is injective if and only if it is vertex inducing.*

# Vertex enumeration

We have enumerated all injective  $\mathcal{N}$ -cfaces, whereas we should have enumerated all vertex-induced  $\mathcal{N}$ -cfaces :-)

## Theorem

*Let  $A \in \text{Mod}$  be a 0-module. Then, a  $A$ -cface is injective if and only if it is vertex inducing.*

## Corollary

*The injective  $\mathcal{N}$ -cfaces are the vertices of  $P$  and Injective cFace Enumeration Algorithm applied to  $C = \mathcal{N}$  computes all vertices of  $P$ .*

## Vertex enumeration

We have enumerated all injective  $\mathcal{N}$ -cfaces, whereas we should have enumerated all vertex-induced  $\mathcal{N}$ -cfaces :-)

### Theorem

*Let  $A \in \text{Mod}$  be a 0-module. Then, a  $A$ -cface is injective if and only if it is vertex inducing.*

### Corollary

*The injective  $\mathcal{N}$ -cfaces are the vertices of  $P$  and Injective cFace Enumeration Algorithm applied to  $C = \mathcal{N}$  computes all vertices of  $P$ .*

Did we not enumerate too many minimal faces on the way?

# Vertex enumeration in total polytime

## Proposition

*Every injective and vertex inducing A-face  $F$  for  $A \in \text{Mod}$  has  $\dim\{x \in P^A : x_F = 0\} \leq k$ .*

# Vertex enumeration in total polytime

## Proposition

*Every injective and vertex inducing  $A$ -cface  $F$  for  $A \in \text{Mod}$  has  $\dim\{x \in P^A : x_F = 0\} \leq k$ .*

**Assume  $P$  is bounded.**

# Vertex enumeration in total polytime

## Proposition

*Every injective and vertex inducing A-face  $F$  for  $A \in \text{Mod}$  has  $\dim\{x \in P^A : x_F = 0\} \leq k$ .*

**Assume  $P$  is bounded.**

Essentially Caratheodory:

# Vertex enumeration in total polytime

## Proposition

*Every injective and vertex inducing A-cface  $F$  for  $A \in \text{Mod}$  has  $\dim\{x \in P^A : x_F = 0\} \leq k$ .*

**Assume  $P$  is bounded.**

Essentially Caratheodory:

## Lemma

*For A-cface  $F$ ,  $A \in \text{Mod}$ , there exist  $\ell \leq k + 1$  vertex inducing A-cfaces  $F^1, \dots, F^\ell$  such that  $F = F^1 \cap F^2 \cap \dots \cap F^\ell$ .*

# Vertex enumeration in total polytime

## Proposition

Every injective and vertex inducing  $A$ -cface  $F$  for  $A \in \text{Mod}$  has  $\dim\{x \in P^A : x_F = 0\} \leq k$ .

Assume  $P$  is bounded.

## Lemma

For  $A$ -cface  $F$ ,  $A \in \text{Mod}$ , there exist  $\ell \leq k + 1$  vertex inducing  $A$ -cfaces  $F^1, \dots, F^\ell$  such that  $F = F^1 \cap F^2 \cap \dots \cap F^\ell$ .

## Proposition

If  $P$  is bounded then holds for all  $A \in \text{Mod}$  that

$$|\{F \subseteq A : F \text{ injective } A\text{-cface}\}| \leq |\{F \subseteq A : F \text{ vertex inducing } A\text{-cface}\}|^{k+1}.$$



# Vertex enumeration in total polytime

## Proposition

*If  $P$  is bounded then holds for all  $A \in \text{Mod}$  that*

$$|\{F \subseteq A : F \text{ injective } A\text{-cface}\}| \leq |\{F \subseteq A : F \text{ vertex inducing } A\text{-cface}\}|^{k+1}.$$

# Vertex enumeration in total polytime

## Proposition

If  $P$  is bounded then holds for all  $A \in \text{Mod}$  that

$$|\{F \subseteq A : F \text{ injective } A\text{-cface}\}| \leq |\{F \subseteq A : F \text{ vertex inducing } A\text{-cface}\}|^{k+1}.$$

## Proposition

For  $A \in \text{Mod}$  holds that

$$|\{F \subseteq A : F \text{ vertex inducing } A\text{-cface}\}| \leq |\mathcal{V}| =: |\{v \in \mathbb{R}^{\mathcal{N}} : v \text{ is a vertex of } P\}|.$$

# Vertex enumeration in total polytime

$$|\{F \subseteq A : F \text{ injective } A\text{-cface}\}| \leq |\{F \subseteq A : F \text{ vertex induced } A\text{-cface}\}|^{k+1}.$$

$$|\{F \subseteq A : F \text{ vertex induced } A\text{-cface}\}| \leq |\mathcal{V}| =: |\{v \in \mathbb{R}^{\mathcal{N}} : v \text{ is a vertex of } P\}|.$$

## Vertex enumeration in total polytime

$$|\{F \subseteq A : F \text{ injective } A\text{-cface}\}| \leq |\{F \subseteq A : F \text{ vertex induced } A\text{-cface}\}|^{k+1}.$$

$$|\{F \subseteq A : F \text{ vertex induced } A\text{-cface}\}| \leq |\mathcal{V}| =: |\{v \in \mathbb{R}^{\mathcal{N}} : v \text{ is a vertex of } P\}|.$$

Let  $t$  time to test for injectiveness and the cface property.

### Theorem

*For  $P$  bounded and  $A, B, C \in \text{Mod}$  with  $C = A \dot{\cup} B$ . Given the set of injective  $A$ -cfaces  $\mathcal{F}^A$  and the set of injective  $B$ -cfaces  $\mathcal{F}^B$ , the set of injective  $C$ -cfaces  $\mathcal{F}^C$  can be computed in time  $O(|\mathcal{V}|^{2k+2}t)$ ,*

# Vertex enumeration in total polytime

## Theorem

*For  $P$  bounded and  $A, B, C \in \text{Mod}$  with  $C = A \dot{\cup} B$ . Given the set of injective  $A$ -cfaces  $\mathcal{F}^A$  and the set of injective  $B$ -cfaces  $\mathcal{F}^B$ , the set of injective  $C$ -cfaces  $\mathcal{F}^C$  can be computed in time  $O(|\mathcal{V}|^{2k+2}t)$ ,*

# Vertex enumeration in total polytime

## Theorem

*For  $P$  bounded and  $A, B, C \in \text{Mod}$  with  $C = A \dot{\cup} B$ . Given the set of injective  $A$ -cfaces  $\mathcal{F}^A$  and the set of injective  $B$ -cfaces  $\mathcal{F}^B$ , the set of injective  $C$ -cfaces  $\mathcal{F}^C$  can be computed in time  $O(|\mathcal{V}|^{2k+2}t)$ ,*

Since there are  $O(\mathcal{N})$  internal nodes in the binary tree defining  $\text{Mod}$ , we have

## Theorem

*For  $P$  bounded its set of vertices can be computed in time  $O(\mathcal{N}|\mathcal{V}|^{2k+2}t)$ ,*

# The power of *k*-modularity?

- ▶ Positive

# The power of $k$ -modularity?

- ▶ Positive
  - ▶ Vertex enumeration in total polynomial time
  - ▶ ILP with positive constraint matrix is FPT if  $\max_i b_i$  is fixed.



# The power of *k*-modularity?

## ▶ Positive

- ▶ Vertex enumeration in total polynomial time
- ▶ ILP with positive constraint matrix is FPT if  $\max_i b_i$  is fixed.
- ▶ LP can be solved in strongly polynomial time if the feasible polyhedron is 1-modular

# The power of $k$ -modularity?

## ▶ Positive

- ▶ Vertex enumeration in total polynomial time
- ▶ ILP with positive constraint matrix is FPT if  $\max_i b_i$  is fixed.
- ▶ LP can be solved in strongly polynomial time if the feasible polyhedron is 1-modular

## ▶ Negative

# The power of $k$ -modularity?

## ▶ Positive

- ▶ Vertex enumeration in total polynomial time
- ▶ ILP with positive constraint matrix is FPT if  $\max_i b_i$  is fixed.
- ▶ LP can be solved in strongly polynomial time if the feasible polyhedron is 1-modular

## ▶ Negative

- ▶ General ILP remains NP-hard even for 3-modular polyhedra

# The power of $k$ -modularity?

## ▶ Positive

- ▶ Vertex enumeration in total polynomial time
- ▶ ILP with positive constraint matrix is FPT if  $\max_i b_i$  is fixed.
- ▶ LP can be solved in strongly polynomial time if the feasible polyhedron is 1-modular

## ▶ Negative

- ▶ General ILP remains NP-hard even for 3-modular polyhedra
- ▶ Deciding if a vertex exists that contains two variables in its support remains NP-hard even for 3-modular polyhedra

# The power of $k$ -modularity?

- ▶ **Positive**
  - ▶ Vertex enumeration in total polynomial time
  - ▶ ILP with positive constraint matrix is FPT if  $\max_i b_i$  is fixed.
  - ▶ LP can be solved in strongly polynomial time if the feasible polyhedron is 1-modular
- ▶ **Negative**
  - ▶ General ILP remains NP-hard even for 3-modular polyhedra
  - ▶ Deciding if a vertex exists that contains two variables in its support remains NP-hard even for 3-modular polyhedra
- ▶ **Open**

# The power of *k*-modularity?

## ▶ Positive

- ▶ Vertex enumeration in total polynomial time
- ▶ ILP with positive constraint matrix is FPT if  $\max_i b_i$  is fixed.
- ▶ LP can be solved in strongly polynomial time if the feasible polyhedron is 1-modular

## ▶ Negative

- ▶ General ILP remains NP-hard even for 3-modular polyhedra
- ▶ Deciding if a vertex exists that contains two variables in its support remains NP-hard even for 3-modular polyhedra

## ▶ Open

- ▶ Vertex enumeration in unbounded *k*-modular polyhedra?

# The power of $k$ -modularity?

## ▶ Positive

- ▶ Vertex enumeration in total polynomial time
- ▶ ILP with positive constraint matrix is FPT if  $\max_i b_i$  is fixed.
- ▶ LP can be solved in strongly polynomial time if the feasible polyhedron is 1-modular

## ▶ Negative

- ▶ General ILP remains NP-hard even for 3-modular polyhedra
- ▶ Deciding if a vertex exists that contains two variables in its support remains NP-hard even for 3-modular polyhedra

## ▶ Open

- ▶ Vertex enumeration in unbounded  $k$ -modular polyhedra?
- ▶ Can LP be solved in strongly polynomial time with  $k$ -modular polyhedra? Or would this imply that general LP can be solved in strongly polynomial time?

# The power of $k$ -modularity?

## ▶ Positive

- ▶ Vertex enumeration in total polynomial time
- ▶ ILP with positive constraint matrix is FPT if  $\max_i b_i$  is fixed.
- ▶ LP can be solved in strongly polynomial time if the feasible polyhedron is 1-modular

## ▶ Negative

- ▶ General ILP remains NP-hard even for 3-modular polyhedra
- ▶ Deciding if a vertex exists that contains two variables in its support remains NP-hard even for 3-modular polyhedra

## ▶ Open

- ▶ Vertex enumeration in unbounded  $k$ -modular polyhedra?
- ▶ Can LP be solved in strongly polynomial time with  $k$ -modular polyhedra? Or would this imply that general LP can be solved in strongly polynomial time?
- ▶ Can the vertex with minimum size support of a  $k$ -modular polyhedron be found in polynomial time?