

Payment Rules for Combinatorial Auctions via Structural Support Vector Machines

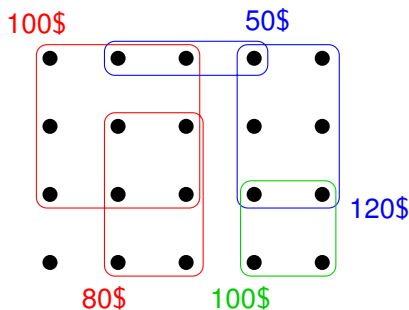
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joint work with Paul Dütting (EPFL), Petch Jirapinyo (Harvard),
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September 7, 2011

Combinatorial Auctions

- ▶ n agents
- ▶ m items
- ▶ Bundles $Y = \{0, 1\}^m$
- ▶ Valuation profiles $X = \mathbb{R}^{2^m \times n}$
- ▶ Allocation rule $g_i : X \rightarrow Y$
- ▶ Payment rule $t_i : X \times Y \rightarrow \mathbb{R}$

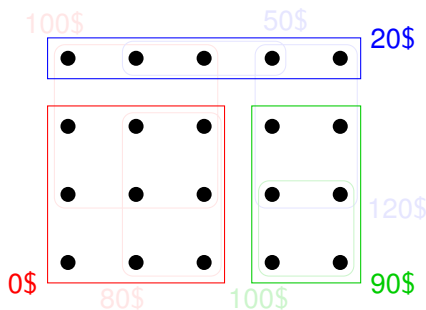


- ▶ Optimal allocation: maximize $\sum_i \mathbf{x}_i[\mathbf{y}_i]$ such that $\mathbf{y}_i \cap \mathbf{y}_j = \emptyset$
- ▶ Strategyproofness:

$$\mathbf{x}_i[g_i(\mathbf{x})] - t_i(\mathbf{x}, g_i(\mathbf{x})) \geq \mathbf{x}_i[g_i(\mathbf{x}'_i, \mathbf{x}_{-i})] - t_i(\mathbf{x}'_i, \mathbf{x}_{-i}, g_i(\mathbf{x}'_i, \mathbf{x}_{-i}))$$

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Problem Statement

- ▶ Elicitation of valuations and computation of optimal allocation are costly, often prohibitively so
- ▶ Canonical strategyproof mechanism: VCG
 - ▶ depends on ability to find efficient allocation
 - ▶ other problems: collusion, small or non-monotonic revenue
- ▶ Alternative solutions hard to come by
- ▶ Our approach: take allocation rule g as given, use to generate input for a learning algorithm
- ▶ Implicitly learns payment rule t that makes g “maximally incentive compatible” (we will see in what sense)

Outline

Combinatorial Auctions and Margin-Based Learning

Learning a Payment Rule

Summary and Open Problems

Learning What We Already Know

- ▶ By symmetry concentrate on agent 1, consider $g = g_1$ and $t = t_1$
- ▶ Assume g is given, as well as a distribution $P(X)$ on X
- ▶ Together they induce a distribution $P(X, Y)$ on $X \times Y$

- ▶ Sample set of training examples from $P(X, Y)$ and learn an allocation function $h : X \rightarrow Y$

Learning What We Already Know

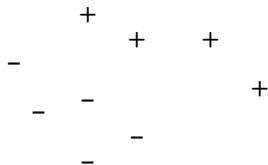
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- ▶ We know g , so we are not actually interested in h
- ▶ Rather: employ a margin-based learning method, infer t from the margin

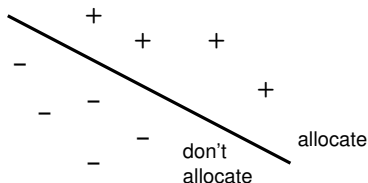
Learning How to Allocate

- ▶ Single-item case corresponds to an ordinary binary classifier:
allocate the item or not



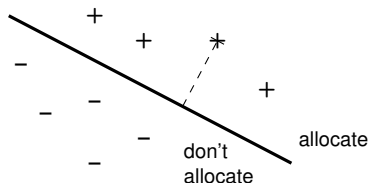
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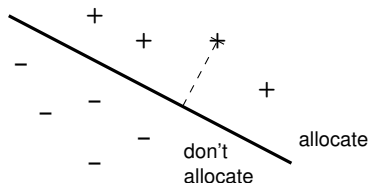
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- ▶ In general: one class for each bundle that could be allocated
- ▶ Learn a discriminant function $f : X \times Y \rightarrow \mathbb{R}$ that rates bundles
- ▶ Define h to choose the most appropriate bundle:

$$h(\mathbf{x}) = \arg \max_{\mathbf{y} \in Y(\mathbf{x}_{-1})} f(\mathbf{x}, \mathbf{y})$$

The Discriminant Function

- ▶ Impose additional structure on f :

$$f_{\mathbf{w}}(\mathbf{x}, \mathbf{y}) = w_1 \mathbf{x}_1[\mathbf{y}] + \mathbf{w}_{-1}^T \psi(\mathbf{x}_{-1}, \mathbf{y})$$

- ▶ $\mathbf{w} = (w_1, \mathbf{w}_{-1}) \in \mathbb{R}^{M+1}$ is a parameter vector to be learned
- ▶ $\psi(\mathbf{x}_{-1}, \mathbf{y}) \in \mathbb{R}^M$ is a feature vector derived from \mathbf{x}_{-1} and \mathbf{y}

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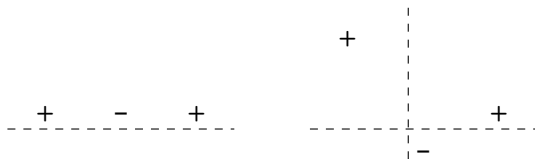
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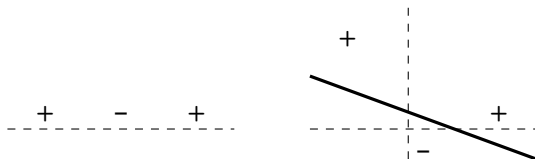


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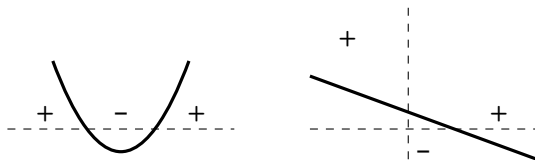


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The Payment Rule

- ▶ Ensure $w_1 > 0$ and let

$$t_{\mathbf{w}}(x, y) = - \left(\frac{\mathbf{w}_{-1}}{w_1} \right)^T \psi(x_{-1}, y)$$

- ▶ agent-independent
- ▶ $h_{\mathbf{w}}$ predicts the utility-maximizing bundle:

$$\begin{aligned} h_{\mathbf{w}}(x) &= \arg \max_{y \in Y(x_{-1})} f_{\mathbf{w}}(x, y) = \arg \max_{y \in Y(x_{-1})} w_1 \mathbf{x}_1[\mathbf{y}] + \mathbf{w}_{-1}^T \psi(\mathbf{x}_{-1}, y) \\ &= \arg \max_{y \in Y(x_{-1})} w_1 \mathbf{x}_1[\mathbf{y}] + \mathbf{w}_{-1}^T \left(- \frac{w_1}{\mathbf{w}_{-1}} t_{\mathbf{w}}(x, y) \right) \\ &= \arg \max_{y \in Y(x_{-1})} (x_1[y] - t_{\mathbf{w}}(x, y)) \end{aligned}$$

- ▶ Can ensure by translation that $\mathbf{w}_{-1}^T \psi(\mathbf{x}_{-1}, \mathbf{0}) = 0$, *i.e.*, that payment for empty bundle is zero

Truthfulness and Regret

- ▶ Looks like the characterization of a strategyproof mechanism, but $h_{\mathbf{w}}$ might not be feasible
- ▶ Also recall that we want to allocate according to g , not $h_{\mathbf{w}}$

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Lemma: The ex-post regret for bidding truthfully in $(g, t_{\mathbf{w}})$ is

$$\frac{1}{w_1} \left(\max_{\mathbf{y}' \in Y(\mathbf{x}_{-1})} f_{\mathbf{w}}(\mathbf{x}, \mathbf{y}') - f_{\mathbf{w}}(\mathbf{x}, g(\mathbf{x})) \right).$$

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Theorem: If $h_{\mathbf{w}}$ is exact, then $(g, t_{\mathbf{w}})$ is strategyproof.

- ▶ But: $h_{\mathbf{w}}$ will not always be exact, we know it cannot be if g is not monotonic

Regret and Generalization Error

- ▶ Generalization error of a classifier $h_{\mathbf{w}} \in \mathcal{H}_{\psi}$:

$$R_P(h_{\mathbf{w}}) = \int_{X \times Y} \Delta_{\mathbf{x}}(\mathbf{y}, h_{\mathbf{w}}(\mathbf{x})) dP(\mathbf{x}, \mathbf{y})$$

where $\Delta_{\mathbf{x}}(\mathbf{y}, \mathbf{y}') = \frac{1}{w_1} (f_{\mathbf{w}}(\mathbf{x}, \mathbf{y}') - f_{\mathbf{w}}(\mathbf{x}, \mathbf{y}))$

Theorem: If $h_{\mathbf{w}}$ minimizes generalization error then $t_{\mathbf{w}}$ minimizes expected ex-post regret for truthful bidding.

- ▶ Amount a random agent can gain by lying when all others tell the truth, for valuations drawn from $P(X)$
- ▶ Different from (approximate) ex-ante and ex-interim equilibrium, rather provides an upper bound on the expected ex-interim gain

Support Vector Machines?

- ▶ Learn a discriminant function that maximizes the margin
- ▶ Binary setting: minimize generalization error in the limit
- ▶ Version with structured/multi-class output due to Joachims et al.
- ▶ Training by solving a quadratic optimization problem with linear constraints, can be done efficiently under certain conditions
- ▶ Training requires computation of inner products in the (high- or infinite-dimensional) feature space \mathbb{R}^M
- ▶ Kernel trick: choose ψ carefully to ensure they can be computed efficiently from vectors in the original space
- ▶ Linear classification in \mathbb{R}^M without any explicit calculations in \mathbb{R}^M

Summary

- ▶ Design of payment rules using margin-based classifier, given oracle access to valuation distribution and allocation rule
- ▶ Exact classifier yields strategyproof payment rule, minimization of error implies minimization of expected ex-post regret
- ▶ Experiments for 5 items, 2 to 6 agents, 200 training examples
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 - ▶ $\psi(x_{-1}, y) = \phi([x_2 \setminus y, \dots, x_n \setminus y])$
 - ▶ ϕ corresponding to RBF kernel $K(z, z') = \exp(-\|z - z'\|/2\sigma^2)$

	accuracy	average regret	IR violation
single item	96%	0.2%	2%
single-minded	90%	1%	6%
multi-minded, complements	94%	0.1%	3%
multi-minded, substitutes	75%	2%	15%

Open Problems

- ▶ Possibly $-\mathbf{w}_{-1}^T \psi(\mathbf{x}_{-1}, \mathbf{y}) \geq \mathbf{x}_1[\mathbf{y}]$, failure of individual rationality
 - ▶ tradeoff between individual rationality and strategyproofness
 - ▶ both at the same time (only?) by deviation from g , e.g., by discarding \mathbf{y} and allocating \emptyset
- ▶ Training problem has $\Omega(|Y(x_{-1})|)$ constraints, exponential in m in general
 - ▶ only polynomially many constraints matter, a separation oracle would suffice
 - ▶ when valuations can be represented succinctly, payment monotonicity would also suffice
 - ▶ more highly structured payment rules for restricted valuations
- ▶ More clever feature maps, e.g., to allow for generalization across different numbers of agents

Thank you!