

Incentive Compatible Regression Learning

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Motivation

- ▶ Goal: *learn* from information held by *strategic agents*
- ▶ Agents have different interests and different ideas of a good output
- ▶ Manipulation to improve result, leads to bias in the training data

- ▶ Machine learning and (algorithmic) mechanism design
- ▶ Two *interrelated* issues: *sampling* and *manipulation*
- ▶ This talk: regression learning

Outline

The Model

- Regression Learning

- The Learning Game

- Mechanism Design (in One Slide)

Three Levels of Generality

- Degenerate Distributions

- Uniform Distributions

- General Distributions

Regression Learning

- ▶ *Input space* \mathcal{X}
- ▶ *Target function* $o : \mathcal{X} \rightarrow \mathbb{R}$, distribution ρ over \mathcal{X} (both unknown)
- ▶ *Hypothesis space* \mathcal{F} of functions $f : \mathcal{X} \rightarrow \mathbb{R}$
- ▶ Loss function $\ell : \mathbb{R}^2 \rightarrow \mathbb{R}$
 - ▶ Absolute loss $\ell(a, b) = |a - b|$
 - ▶ Squared loss $\ell(a, b) = (a - b)^2$
- ▶ Risk (disutility) $R(f) = \mathbb{E}_{\mathbf{x} \sim \rho}[\ell(f(\mathbf{x}), o(\mathbf{x}))]$ associated with $f \in \mathcal{F}$
- ▶ Regression learning
Given training set $S = \{(\mathbf{x}_j, o(\mathbf{x}_j))\}_{j=1, \dots, m}$, \mathbf{x}_j sampled i.i.d. from ρ , find $h \in \arg\min_{f \in \mathcal{F}} R(f)$

Regression Learning with Strategic Agents

- ▶ *Input space* \mathcal{X}
- ▶ Set N of strategic agents
- ▶ *Target functions* $o_i : \mathcal{X} \rightarrow \mathbb{R}, i \in N$
- ▶ Distributions ρ_i over $\mathcal{X}, i \in N$
- ▶ *Hypothesis space* \mathcal{F}
- ▶ Risk $R_i(f) = \mathbb{E}_{\mathbf{x} \sim \rho_i}[\ell(f(\mathbf{x}), o_i(\mathbf{x}))]$
- ▶ Goal: minimize $\mathbb{E}_J[R_J(h)]$, where J is a random variable distributed uniformly over N (i.e., maximize social welfare)

- ▶ Training set?

The Learning Game

- ▶ Agent i controls \mathbf{x}_{ij} , $j = 1, \dots, m$, sampled i.i.d. from ρ_i
- ▶ $y_{ij} = o_i(\mathbf{x}_{ij})$ is private information
- ▶ Agent i reveals \hat{y}_{ij} , $j = 1, \dots, m$
- ▶ True sample $\mathcal{S} = \{\mathcal{S}_i : i \in N\}$, $\mathcal{S}_i = \{(\mathbf{x}_{ij}, y_{ij}) : 1 \leq j \leq m\}$
- ▶ Training set $\hat{\mathcal{S}} = \{\hat{\mathcal{S}}_i : i \in N\}$, $\hat{\mathcal{S}}_i = \{(\mathbf{x}_{ij}, \hat{y}_{ij}) : 1 \leq j \leq m\}$
- ▶ Empirical Risk $\hat{R}(f, \mathcal{S}) = \frac{1}{|\mathcal{S}|} \sum_{(\mathbf{x}, y) \in \mathcal{S}} \ell(f(\mathbf{x}), y)$
- ▶ Empirical Risk Minimization (ERM): minimize $\hat{R}(f, \hat{\mathcal{S}})$

- ▶ Two issues: *sampling* and *manipulation*

Mechanism Design Terminology

- ▶ ERM is
 - ▶ a *social choice function*
 - ▶ economically *efficient*, *i.e.*, maximizes social welfare
- ▶ *Mechanism*: social choice function plus a payment function
 - ▶ *strategyproof* if agent i cannot increase payoff (*i.e.*, decrease sum of risk and payment) by revealing a $\hat{y}_{ij} \neq y_{ij}$
 - ▶ *group strategyproof* if no group can (weakly) increase the payoff of all members

- ▶ *Why strategyproofness?*
Otherwise: no well-defined input to the learning problem, no theoretical guarantees

Degenerate Distributions: ERM with Absolute Loss

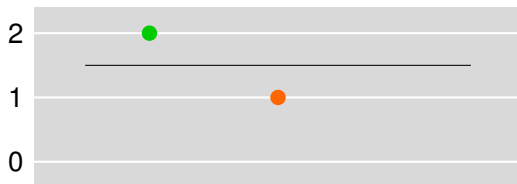
- ▶ Distribution ρ_i degenerate at \mathbf{x}_i
- ▶ Agent i holds $y_i = o_i(\mathbf{x}_i)$ and reveals \hat{y}_i
- ▶ $\hat{S} = \{(\mathbf{x}_i, \hat{y}_i) : i \in N\}$
- ▶ $h = \operatorname{argmin}_{f \in \mathcal{F}} \hat{R}(f, \hat{S}) = \operatorname{argmin}_{f \in \mathcal{F}} \sum_{i \in N} \ell(f(\mathbf{x}_i), \hat{y}_i)$
- ▶ Agent i incurs cost $R_i(h) = \hat{R}(h, S_i) = \ell(h(\mathbf{x}_i), y_i)$
- ▶ **Theorem:** If ℓ is the *absolute loss* and \mathcal{F} is convex, then ERM is group strategyproof.
Actually: if we don't get the (real) best fit, then somebody must have lied and lost

ERM with Superlinear Loss

- ▶ **Theorem:** If ℓ is “superlinear”, \mathcal{F} is convex, not “full” on $\mathbf{x}_1, \dots, \mathbf{x}_n$, and contains at least two functions, then ERM is *not* strategyproof.

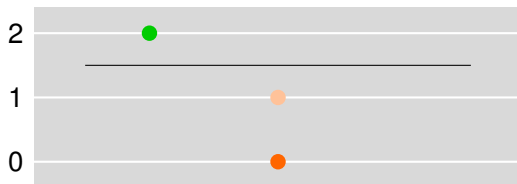
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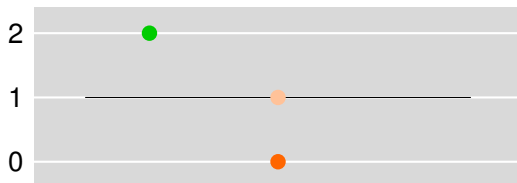
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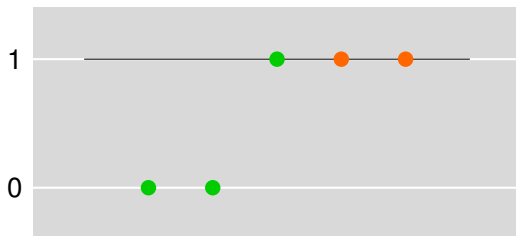


Uniform Distributions

- ▶ Distribution ρ_i discrete, uniform over $\{\mathbf{x}_{i1}, \dots, \mathbf{x}_{im}\}$
- ▶ Agent i holds $y_{ij} = o_i(\mathbf{x}_{ij})$ and reveals $\hat{y}_{ij}, j = 1, \dots, m$
- ▶ ERM computes $h = \operatorname{argmin}_{f \in \mathcal{F}} \hat{R}(h, \hat{S})$
- ▶ Agent i incurs cost $R_i(h) = \hat{R}(h, S_i) = \frac{1}{m} \sum_{j=1}^m \ell(h(\mathbf{x}_{ij}), y_{ij})$

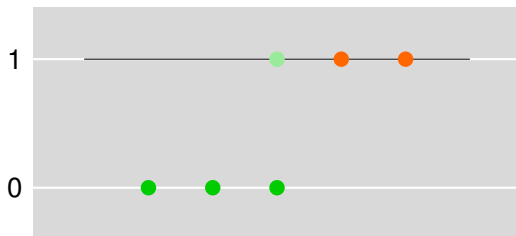
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- ▶ ERM with absolute loss no longer strategyproof



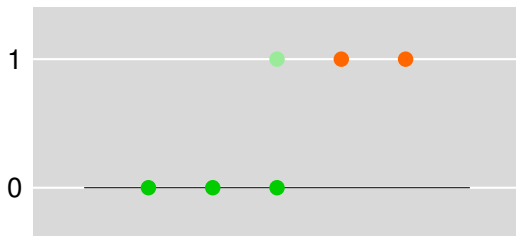
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VCG to the Rescue

- ▶ General Mechanism due to Vickrey (1961), Clarke (1971), and Groves (1973)
- ▶ Perform ERM (recall: it is economically efficient)
- ▶ Agent i pays $\sum_{j \neq i} \hat{R}_j(h, \hat{S}_j)$,
incurs total cost $\hat{R}(h, S_i) + \sum_{j \neq i} \hat{R}(h, \hat{S}_j)$
- ▶ Good news: strategyproof for any loss function
- ▶ Bad news
 - ▶ in general: not group strategyproof, payments problematic
 - ▶ in our case: payments not bounded, no obvious way to ensure individual rationality
- ▶ Is there a (group) strategyproof mechanism without payments?

Mechanisms without Payments

- ▶ Absolute loss function
- ▶ Relax efficiency requirement, consider α -efficient mechanisms
- ▶ **Theorem (upper bound):** There exists a 3-efficient, group strategyproof mechanism for constant functions over \mathbb{R}^k and homogeneous linear functions over \mathbb{R}

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- ▶ **Theorem (lower bound):** There is no $(3 - \varepsilon)$ -efficient, strategyproof mechanism for constant or homogeneous linear functions over \mathbb{R}^k for any k and any $\varepsilon > 0$

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- ▶ **Theorem (lower bound):** There is no $(3 - \varepsilon)$ -efficient, strategyproof mechanism for constant or homogeneous linear functions over \mathbb{R}^k for any k and any $\varepsilon > 0$
- ▶ **Conjecture:** There is no α -efficient, strategyproof mechanism without payments for homogeneous linear functions over \mathbb{R}^k for $k \geq 2$ and any α

Generalization

- ▶ Assume that for all $f \in \mathcal{F}$,
 - (a). for all $i \in N$, $|\hat{R}_i(f, S) - R_i(f)| \leq \frac{\varepsilon}{2}$ and
 - (b). $|\hat{R}(f, S) - \frac{1}{n} \sum_{i \in N} R_i(f)| \leq \frac{\varepsilon}{2}$
- ▶ Then the following holds for any mechanism:
 - ▶ If (group) strategyproof under uniform distributions, then ε -(group) strategyproof under general distributions
 - ▶ If α -efficient under uniform distributions, then α -efficient under general distributions up to an additive factor of ε
- ▶ If \mathcal{F} has bounded complexity and sample size is $\Theta\left(\frac{\log(1/\delta)}{\varepsilon^2}\right)$, then (a) holds with probability $1 - \delta$
- ▶ (b) holds if (a) holds for all i , increasing the sample size by a $\log|N|$ factor

Discussion

- ▶ For m large enough, any loss function, any function class: VCG is ε -strategyproof with probability $1 - \delta$
- ▶ For m large enough, absolute loss, constant functions: there exists a mechanism without payments that is ε -group strategyproof and 3-efficient (up to additive ε)
- ▶ Future work:
 - ▶ Settle impossibility conjecture for homogeneous linear functions over \mathbb{R}^k
 - ▶ Extend to other settings, e.g. classification

Thank you for your attention!