Experiment Design Based on Bayes Risk and Weighted Bayes Risk with Application to Pharmacokinetic Systems

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Supported by NIH Grants GM 068968 and HD 070886 Questions? David Bayard (dbay007@earthlink.net)

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Introduction

• Multiple Model Optimal (MMOpt) Design

- Captures essential elements of Bayesian Experiment Design without the excessive computation
- Minimizes a recent theoretical overbound on the Bayes Risk (Blackmore et. al. 2008 [4])
- Intended for multiple model (MM) parametrizations which form the basis of the USC BestDose software (corresponds to the support points in a nonparametric population model)
- Has several advantages relative to D-optimality and other criteria based on the asymptotic Fisher Information matrix for <u>nonlinear problems</u>
- Contribution of present paper, since the last PODE, is to generalize MMOpt by introducing a weighting into the Bayes Risk Cost
 - New result shows that simple analytical overbound of [4] is preserved in the weighted case
 - Weights allow MMOpt experiment design to address many problems of practical interest (AUC estimation, what best future dose to give, etc.)
- Numerical examples demonstrate MMOpt on several relevant PK problems

• Dynamic Model and Measurements

 $\dot{x}(t) = f(x(t), d(t), \theta)$ State x, Input d, Parameter $\theta \in R^p$ $\eta_k = h(x(t_k), \theta)$, System output at time t_k $y_k = \eta_k + \sigma_k n_k$, Noisy measurement at time t_k $n_k \sim N(0, 1)$, Gaussian measurement noise $\xi = \{t_1, ..., t_n\}$, Experiment design (optimal sampling)

• D-Optimal Design

 $\max_{\xi} |M|$

where the Fisher Information Matrix M is given by,

$$M(\theta,\xi) = \sum_{k=1}^{n} \frac{1}{\sigma_k^2} \left[\frac{\partial \eta_k}{\partial \theta} \frac{\partial \eta_k}{\partial \theta^T} \right] \Big|_{\theta = \overline{\theta}}$$

Herein, M(θ, ξ) is assumed to be a function of θ

 (i.e., nonlinear problems)

D-Optimal Design for Nonlinear Problems

- D-optimality (traditional) maximizes the determinant of the Fisher Information Matrix (Fedorov 1972 [20], Silvey 1980 [19])
 - max |M|, where M is Fisher Information Matrix, and |(.)| is determinant
 - Useful tool has become standard in design of clinical experiments
- For nonlinear problems, MMOpt offers several advantages relative to Doptimality and other criteria based on the asymptotic Fisher Information matrix
 - Avoids circular reasoning associated with having to know a patient's true parameters in order to design an experiment
 - Avoids using an asymptotic information measure when placing only a small number of samples
- To robustify D-optimal design, an expectation is taken with respect to certain functions of prior information giving rise to ED, EID, and ELD (or API) optimal designs
 - Chaloner [13], Pronzato [14][15], Tod [16], D'Argenio [17]

Definition of ED, EID, API

• Robust D-Optimal Designs

ED: $\arg \max_{\xi} E_{\theta} \left(|M| \right)$ EID: $\arg \min_{\xi} E_{\theta} \left(\frac{1}{|M|} \right)$ API: $\arg \max_{\xi} E_{\theta} \left(\log |M| \right)$ where, $\theta \in \mathbb{R}^{p}$ - Parameter Vector $\eta = \{t_{1}, ..., t_{n}\}$ - Experiment design

M - Fisher Information Matrix

 All above design metrics require Fisher Matrix M to be nonsingular, and hence require at least p samples to be taken, where p=# parameters

Multiple Model Optimal Design

- USC BestDose software [3] is based on a multiple model (MM) parametrization of the Bayesian prior (i.e., discrete support points in the <u>nonparametric population</u> model)
 - Nonparametric Maximum Likelihood (NPML) estimation of a population model has the form of a MM prior (Mallet [5], Lindsay [6]).
 - Software for population NPML modeling is available, e.g., NPEM (Schumitzky [7][11]), NPAG (Leary [8], Baek [9]), USC*PACK (Jelliffe [10], and **Pmetrics** in Bestdose [3].



- Experiment design for MM (i.e., discrete) models is a subject found in classification theory
 - How do we sample the patient to find out which support point he best corresponds to?
 - Classifying patients is fundamentally different from trying to estimate patient's parameters
- Treating MM experiment design in the context of classification theory leads to the mathematical problem of <u>minimizing Bayes risk</u> (Duda et. al. [21])

Multiple Model Optimal Design (MMOpt)

• Bayes Rule

 $p(H_i|y, u) = \frac{p(y|H_i, u)p(H_i)}{p(y|u)}, \quad i = 1, ..., m$ H_i - Hypothesis that model *i* corresponds to true subject *u* - Experiment design variable (to be optimized over)

• Design Rule for MM Classifier

If $p(H_j|y, u) = \max_i \{ p(H_i|y, u) \}$, then

1. H_j is classified as TRUE

(i.e., j'th model is classified as true subject)

2. H_i for $i \neq j$ is classified as FALSE

• Design Regions

MM classifier breaks y into m regions R_i , i = 1, ..., msuch that H_j is classified as TRUE when $y \in R_j$. Multiple Model Optimal Design (Cont'd)

- Bayes Risk (i.e., Probability of MM Classifier Being Wrong)
 P(error) = ∑_i^m ∑_{j≠i}^m P(y ∈ R_j, H_i|u) (Sum of probabilities over all possible ways of making a mistake)
- Bayes Risk represents a cost function to be minimized
 - Consistent with a Bayesian experiment design philosophy
- Result: (Blackmore et. al. 2008)

The Bayes Risk is upper bounded as follows:

$$P(error) \leq \sum_{i=1}^{m} \sum_{j>i=1}^{m} P(H_i)^{\frac{1}{2}} P(H_j)^{\frac{1}{2}} e^{-k(i,j)}$$

where,

$$k(i,j) = \frac{1}{4}(\mu(j) - \mu(i))^T \left(\Sigma(i) + \Sigma(j)\right)^{-1} (\mu(j) - \mu(i)) + \frac{1}{2} \ln \frac{|\frac{1}{2}(\Sigma(i) + \Sigma(j))|}{\sqrt{|\Sigma(i)||\Sigma(j)|}}$$

• MMOpt minimizes upper bound (1) on the probability that the true subject will be incorrectly classified

(1)

Model Response Separation r(t)

 Model Response Separation r(t) is the separation between two model responses at a given time t

$$r(t) = |\eta(t, a_1) - \eta(t, a_2)|$$

•Defines natural statistic for discriminating between two models







• Models are best discriminated by sampling at a time t that maximizes r(t)

MMOpt Example: 4-Models (1/2)

- Two-Parameters a, b $y_i = \eta(t_i, a, b) + \sigma n_i$ $\eta(t, a, b) = be^{-at}$ $n_i \sim N(0, \sigma^2)$ $\sigma = 0.1$
- Prior: $p_i = .25, i = 1, ..., 4$

Model Parameters						
#	a b					
1	2	2.625				
2	1	0.6				
3	0.7	0.6				
4	0.5	0.6				



MMOpt Example: 4-Models (2/2)

Design Metric	2-Sample Times		Bayes Risk	Bayes Risk
				99%Conf *
MMOpt	0.45	1.4	0.32839	+/- 0.00070
ED	0	0.8	0.37028	+/- 0.00070
EID	0	1	0.36044	+/- 0.00072
API	0	0.95	0.36234	+/- 0.00072

Design Metric	3-Sample Times			Bayes Risk	Bayes Risk
				99% Conf *	
MMOpt	0.45	1.4	1.4	0.28065	+/- 0.00067
ED	0	0.7	0.9	0.32048	+/- 0.00067
EID	0	0	1	0.36034	+/- 0.00072
API	0	0.85	0.105	0.3099	+/- 0.00069

• MMOpt has smallest Bayes Risk of all designs studied

* evaluated based on Monte Carlo analysis using 1,400,000 runs per estimate

Comparison Table

	ED	EID	API	MMOpt
Invariant under regular <u>linear</u> reparametrization*	Yes	Yes	Yes	Yes
Invariant under regular <u>nonlinear</u> reparametrization*	No	Νο	Yes	Yes
Allows taking fewer than p samples, p= # of parameters	No	No	No	Yes
Can handle heterogeneous model structures	No	No	No	Yes
Gives known optimal solution to 2-model example [*]	No	Νο	No	Yes
Captures main elements of minimizing Bayes risk	No	No	No	Yes

*Proved in Bayard et. al., PODE 2013 [23]

Weighted MMOpt

- Introduce weights $\{c_{ij}\}$ to specify a cost for each type of classification error
- Assign c_{ij} as the cost of mistaking truth subject *i* for subject *j* $(j \neq i)$
- Choice of weights tailors experiment design to desired applications of interest



Weighted MMOpt

• Weighted Bayes Risk (i.e., Expected Cost of MM Classifier Being Wrong)

 $C(error) = \sum_{i=1}^{m} \sum_{j \neq i=1}^{m} c_{ij} P(y \in R_j, H_i | u)$

(Sum of costs over all possible ways of making a mistake)

Here, c_{ij} is the cost of mistaking subject *i* for subject *j* $(j \neq i)$

• Useful Result (new)

The Weighted Bayes Risk is upper bounded as follows:

$$C(error) \leq \sum_{i}^{m} \sum_{j \neq i}^{m} \overline{c}_{ij} P(H_i)^{\frac{1}{2}} P(H_j)^{\frac{1}{2}} e^{-k(i,j)}$$

where,

$$k(i,j) = \frac{1}{4}(\mu(j) - \mu(i))^T \left(\Sigma(i) + \Sigma(j)\right)^{-1} (\mu(j) - \mu(i)) + \frac{1}{2} \ln \frac{|\frac{1}{2}(\Sigma(i) + \Sigma(j))|}{\sqrt{|\Sigma(i)||\Sigma(j)|}}$$

 $\overline{c}_{ij} = \max\left(c_{ij}, c_{ji}\right)$

- Result allows weighted bound-optimal designs to be systematically calculated as in the unweighted MMopt case
- Weighted MMOpt minimizes upper bound (2) on the expected cost associated with the true subject being incorrectly classified

(2)

Applications of MMOpt

Three Numerical Examples

- PK Estimation (unweighted MMOpt)
- AUC Estimation (weighted MMOpt)
- AUC Control (weighted MMOpt)
- Results will be compared to ED optimal design EDopt
 - Also compared to Bayes optimal design Bopt when computationally feasible to do so

PK Population Model with 10 Multiple Model Points - First-Order PK Model



Unweighted MMOpt for PK Estimation

• Summary of optimal 1,2 and 3 sample designs applied to PK Estimation

Design Metric	Samples			Bayes Risk	99% conf
	(hr)			(prob)	(prob)
	1-Sample Design				
Bopt	4.25			0.5474	± 0.0015
MMopt	4.25			0.5474	± 0.0015
	2-Sample Design				
MMopt	1	9.5		0.2947	± 0.0014
EDopt	1	24		0.3272	± 0.0014
	3-Sample Design				
MMopt	1 1 10.5		0.2325	± 0.0013	
EDopt	1	1	24	0.2617	± 0.0013

- <u>1 Sample Design</u>: MMOpt performance equals Bayesian optimal design (both have Bayes Risk of 0.5474).
- MMOpt performance improves on EDopt design for 2 and 3 sample designs
 - <u>2 Sample Design</u>: Bayes Risk of 0.29 versus 0.33
 - <u>3 Sample Design</u>: Bayes Risk of 0.23 versus 0.26
- All results are statistically significant to p<0.0001

Weighted MMOpt for AUC Estimation

- OBJECTIVE: Design an experiment which is most informative about estimating patient's AUC
 - In this case MMopt weights are chosen as

$$c_{ij} = \left(\frac{D}{V_i K_i} - \frac{D}{V_j K_j}\right)^2$$

= Squared AUC error incurred if j'th subject's

AUC is used to estimate i'th subject's AUC



Dose input D = 300 (300 units of drug infused over 1 hour)

#	AUC Responses
1	29.2767
2	28.7684
3	50.2902
4	30.9562
5	25.9683
6	93.5811
7	27.0741
8	115.8003
9	31.7176
10	31.1448
Mean	46.4578
STD	30.2314

AUC responses to dose D_{18}

Weighted MMOpt for AUC Estimation (Cont'd)

• Summary of optimal 1,2 and 3 sample designs applied to AUC estimation

Design Metric	Samples			RMS Error	$99\% \mathrm{conf}$
	(hr)			(AUC units)	(AUC units)
	1-Se	ample D	esign		
$Bopt_C_2$	24			5.9059	± 0.0270
$MMopt_C_2$	14			6.9789	± 0.0265
MMopt	4.25			21.6806	± 0.0919
	2-Sample Design				
$MMopt_C_2$	1	13		1.8386	± 0.0231
MMopt	1	9.5		2.2346	± 0.0483
EDopt	1	24		2.2079	± 0.0211
	3-Sample Design				
$MMopt_C_2$	1	10.25	10.25	1.4042	± 0.0175
MMopt	1	1	10.5	1.7025	± 0.0382
EDopt	1	1	24	1.8949	± 0.0188

- <u>1 Sample Design</u>: Weighted MMOpt performance approximates that of the Weighted Bayesian optimal design (RMS error of 6.98 versus 5.9 AUC units)
- MMOpt performance improves on EDopt design
 - <u>2 Sample Design</u>: RMS error of 1.84 versus 2.21 (units of AUC)
 - <u>3 Sample Design</u>: RMS error of 1.40 versus 1.89 (units of AUC)
- All results are statistically significant to p<0.0001

Weighted MMOpt for AUC Control

- OBJECTIVE: Design an experiment most informative about next dose needed for patient to achieve a specified AUC of $\alpha_{des} = 40$
 - In this case MMopt weights are chosen as

#	Ideal Dose
1	409.8827
2	417.1242
3	238.6149
4	387.6442
5	462.1011
6	128.2311
7	443.2281
8	103.6267
9	378.3394
10	385.2965
Mean	335.4089
STD	35.8470

$$c_{ij} = (\frac{D_j}{V_i K_i} - \alpha_{des})^2$$

= Squared AUC error incurred if j'th subject's ideal dose D_j is given to i'th subject

	j = 1	j=2	j = 3	j = 4	j = 5	j = 6	j = 7	j = 8	j = 9	j = 10
i = 1	0	0.499	279	4.70	25.9	755	10.5	893	9.47	5.75
i = 2	0.482	0	293	7.99	18.6	767	6.26	903	13.8	9.31
i = 3	824	895	0	624	1403	342	1176	512	548	604
i = 4	5.26	9.25	236	0	59.0	716	32.8	858	0.921	0.0586
i = 5	20.4	15.1	374	41.5	0	835	2.66	962	52.5	44.2
i = 6	771	8121	1185	6548	10846	0	9654	58.9	6086	6430
i = 7	9.05	5.54	340	25.1	2.90	808	0	939	34.2	27.3
i = 8	13975	14643	2715	12019	19147	90.1	17184	0	11244	11821
i = 9	11.1	16.8	218	0.967	78.4	699	47.0	843	0	0.541
i = 10	6.51	10.9	231	0.0594	63.5	712	36.1	855	0.521	0

Ideal Doses $\{D_j\}$ to achieve desired AUC of $\alpha_{des} = 40$

Matrix of Weights $\{c_{ij}\}$

Weighted MMOpt for AUC Control (Cont'd)

• Summary of optimal 1,2 and 3 sample designs applied to AUC control

Design Metric	Samples			RMS Error	99% conf
	(hr)			(AUC units)	(AUC units)
	1-Sample Design				
$Bopt_C_1$	12.5			3.6194	± 0.0273
$MMopt_C_1$	14			3.7729	± 0.0166
MMopt	4.25			16.7924	± 0.1145
	2-Sample Design				
$MMopt_C_1$	1	13		2.1102	± 0.0125
MMopt	1	9.5		2.2575	± 0.0232
EDopt	1	24		2.6159	± 0.0174
	3-Sample Design				
$MMopt_C_1$	1	10.25	10.25	1.6967	± 0.0078
MMopt	1	1	10.5	1.9991	± 0.0192
EDopt	1	1	24	2.4194	± 0.0174

- <u>1 Sample Design</u>: weighted MMOpt performance approximates that of the weighted Bayesian optimal design (RMS error of 3.62 versus 3.77 AUC units)
- MMOpt performance improves on EDopt design for 2 and 3 sample designs
 - <u>2 Sample Design</u>: RMS error of 2.11 versus 2.62 (units of AUC)
 - <u>3 Sample Design</u>: RMS error of 1.70 versus 2.42 (units of AUC)
- All results are statistically significant to p<0.0001

Summary

- Multiple Model Optimal Design (MMOpt) provides an alternative approach to designing experiments
 - Particularly attractive for Nonparametric Models (MM discrete prior)
 - Based on true MM formulation of the problem (i.e., classification theory)
 - Has several advantages relative to ED, EID and API (last year's PODE [23])
 - Based on recent theoretical overbound on Bayes Risk (Blackmore et. al. 2008 [4])
- Introduced Weighted version of MMOpt which minimizes upper bound on the Weighted Bayes Risk
 - Allows specification of costs for each type of classification error
 - Preserves overbound property so that weighted MMOpt designs are as straightforward to compute as unweighted MMOpt designs
 - Examples show that weighted MMOpt performance improves on EDopt, and compares favorably to the theoretically best performance of the weighted Bayes optimal classifier
- MMOpt captures essential elements of Bayesian Experiment Design without the excessive computation
 - Bayesian formulation of design problem for multiple model problems
 - Allows approximate pre-posterior analysis "without tears"
 - To be included in a future release of the USC BestDose software [3]

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